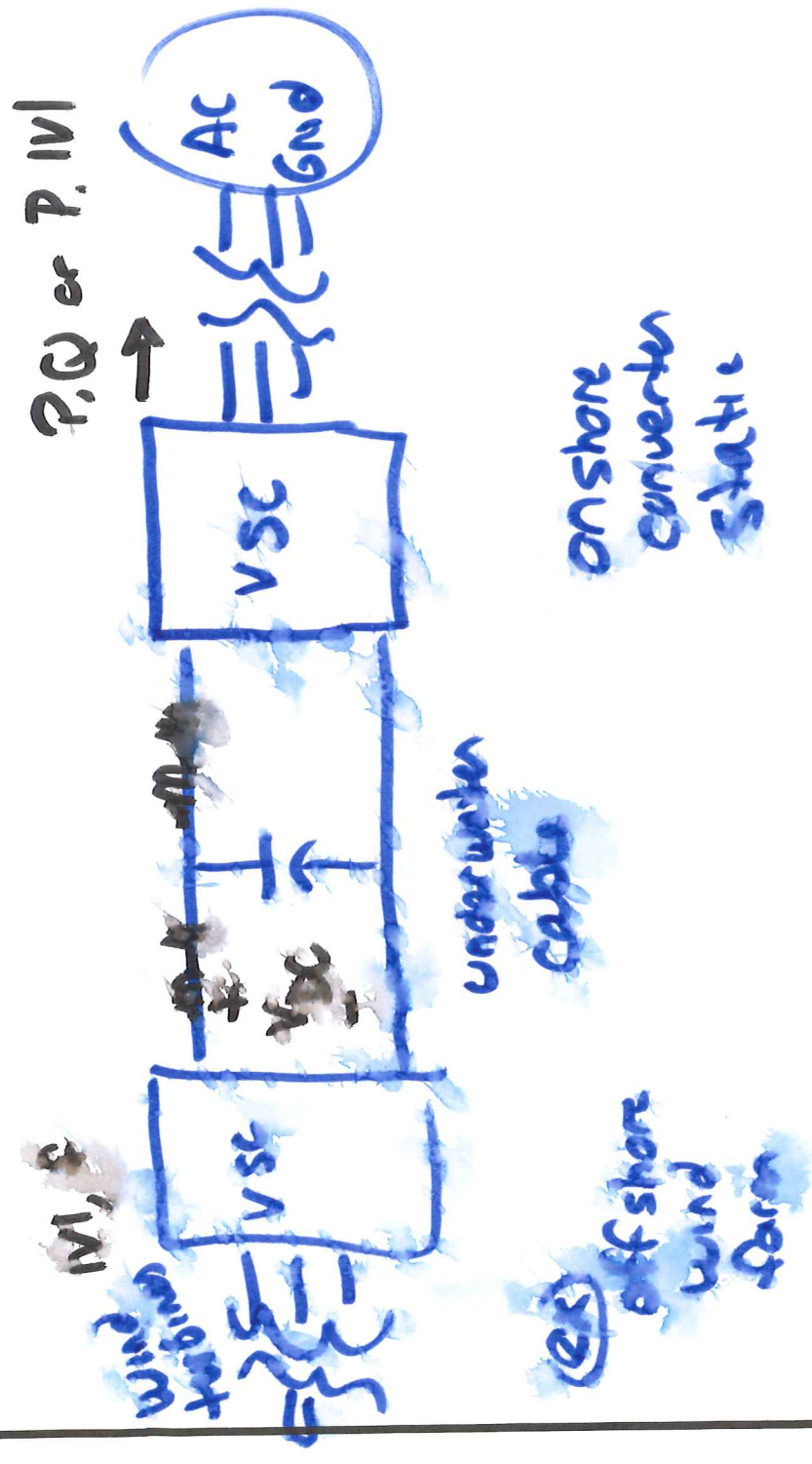


ECE 404-TD / 504-TD

ST: T&D APPLICATIONS OF  
VOLTAGE SOURCE CONVERTERS

SESSION no. 25

Passive Applications - Voltage SC High Voltage DC transmission



$\omega_{meas}$  or  $V_{acl}$

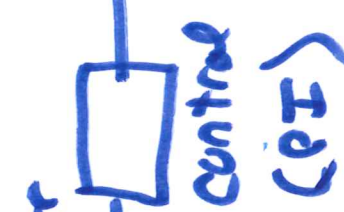
$\omega_{ref}$  or  $V_{ref}$

Q axis reference aligned with VA D axis - 90 deg off from VA

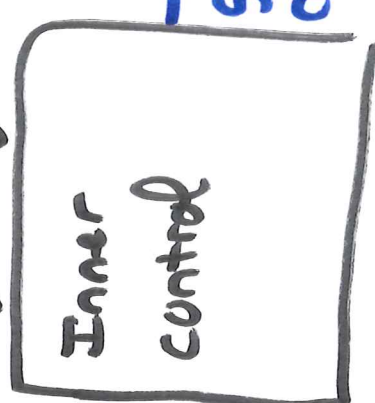
$i_{dmeas}$   $i_{qmeas}$



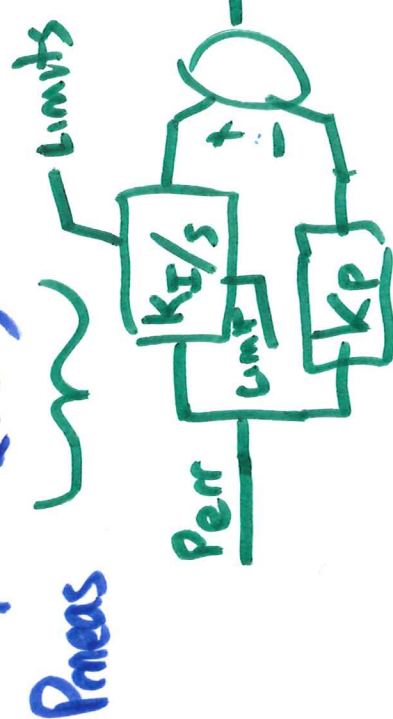
$I_{dref}$



$I_{qref}$



gate control



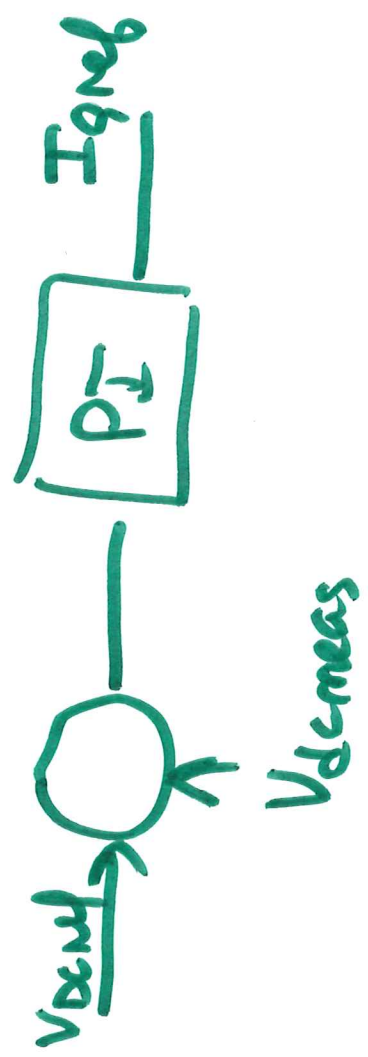
fast response

- generate commands for switching
- fundamental frequency cycle or less

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for converter controlling  $V_{dc}$

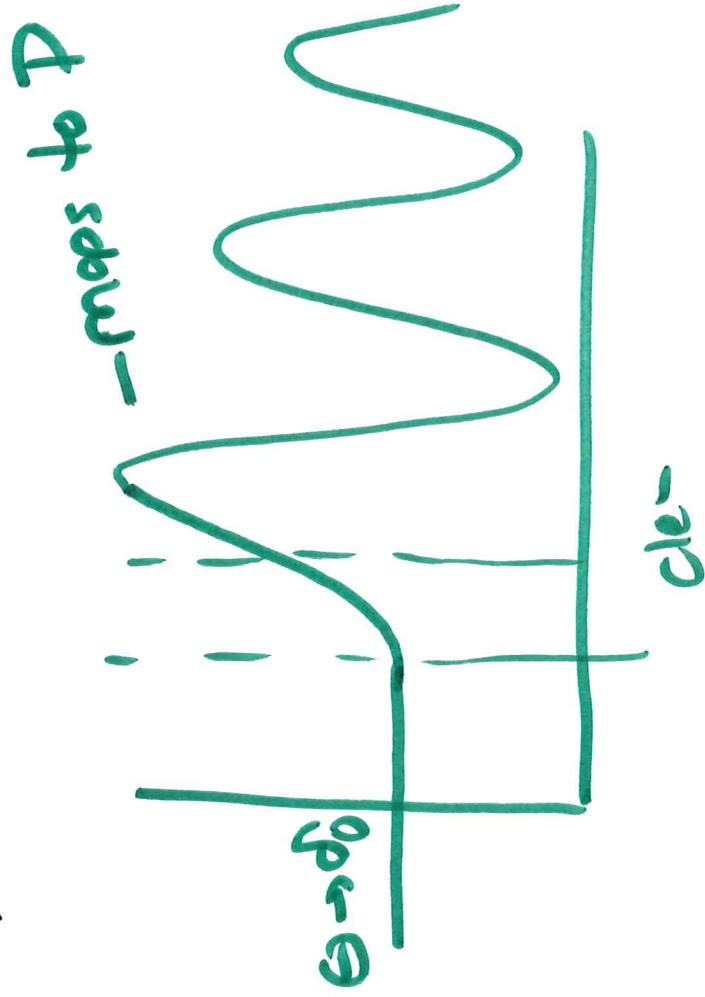


→ replaces Power control at a converter

→

## Supplemental outer loop controls

- Power oscillation damping
  - Grid connected converters
  - low frequency oscillation due to disturbance
    - modulate  $P$  ( $\cos \theta$ ) to damp disturbance
- Sub synchronous resonance damping



$\mathcal{Q}$  (MI) will oscillate with  
90° shift

## Model converters for

- (1) system studies
- (2) control design

Options: (1) fully detailed switching model

- model all of the devices
  - model turn-on/turn-off behavior
- Impractical
- system dynamics of interest are much slower than

device turn-on/turn-off

## (2) Simplified switching models

- Ideal switches or quasi ideal

→ model 1 device instead

of series string

Time steps  
1  $\mu$ s - 5  $\mu$ s

- don't model turn-on / turn-off behavior in detail

- don't model diode in detail

EMTP-like

Programs  
ATP, EMTDC  
RTDS

- Not ~~more~~ necessarily model all converter modules



- Don't model system startup in detail

- Doesn't represent losses very well

- approximations

① Add a series voltage drop

② Add a series resistor (small) to represent resistive part of forward drop

(3) Add a voltage dependant  
current source ~~to~~ on  
dc link for switching  
losses

for most system studies neglecting  
losses has a small impact

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- full ~~swing~~ <sup>switching</sup> switching models  
are a late stage model for

Studies

- Non-Switching models

(1) Power Flow models

regulated  $P, |V|$

on  $P, Q$  or whatever

control goals are

- with limits added

## ② Stability Studies

- add outer control loops

- some of the averaged dynamics of converter

## ③ Fault Studies

- voltage source with current control/limits

Possible ← OF  
Phase shift to leading current  
current source

④ Transient studies / control dc

equivalent AC voltage source  $\left\{ \begin{array}{l} \rightarrow \text{Fundamental component models} \\ \text{or} \\ \text{Averaged models} \end{array} \right.$

$\rightarrow$  equivalent dc current source