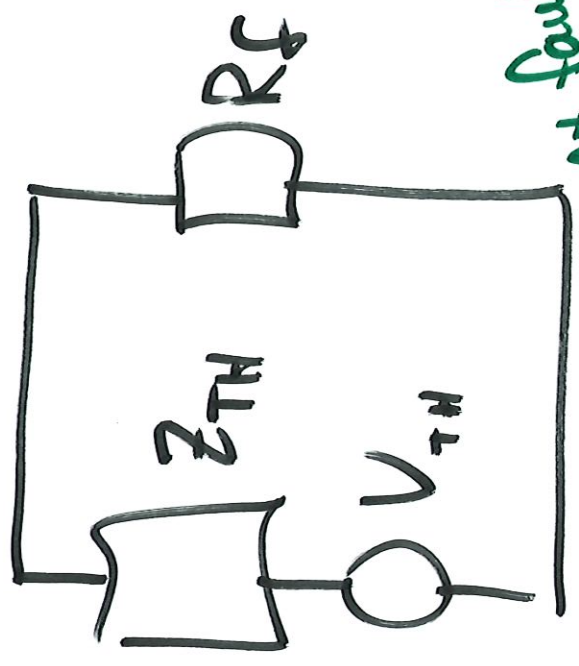
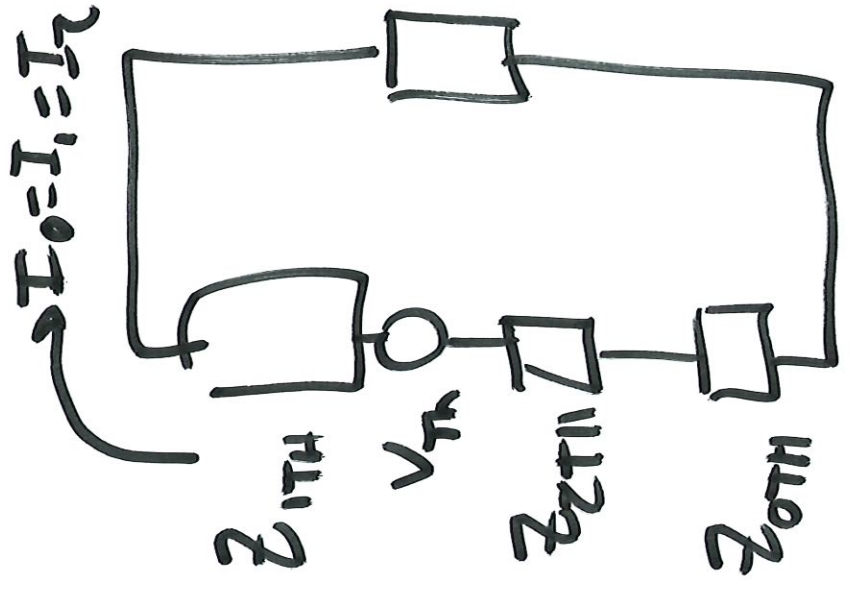


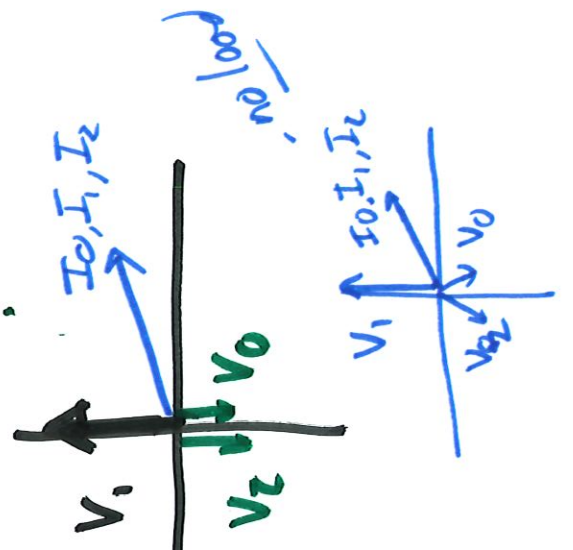
ECE 523
Symmetrical Components

Session 15

Three phase faults
 → pos sep
 → Z_f

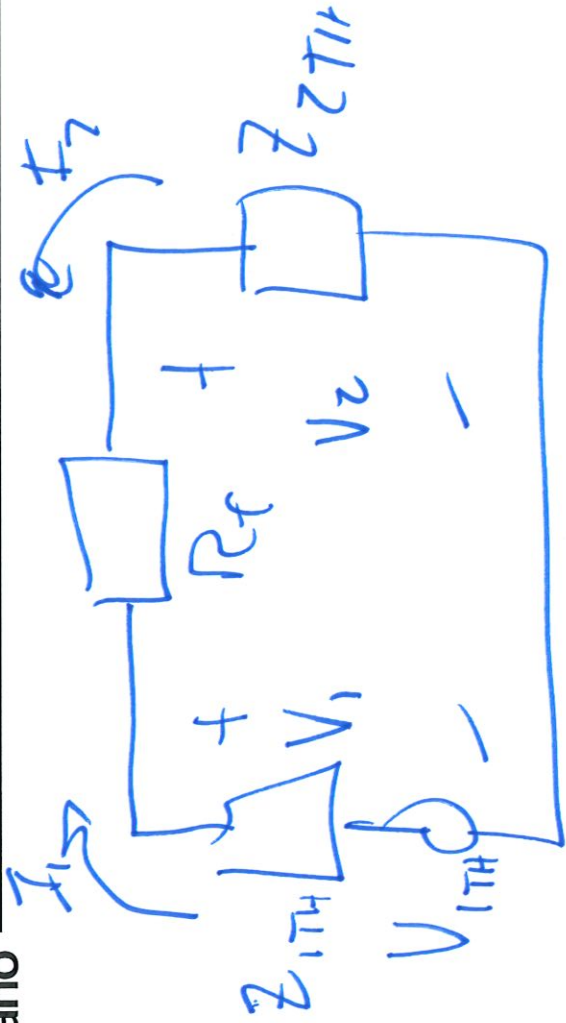


At fault loc.
 $V_1 + V_2 + V_0 = 3I_0 R_f$



at bus
 at end of ln

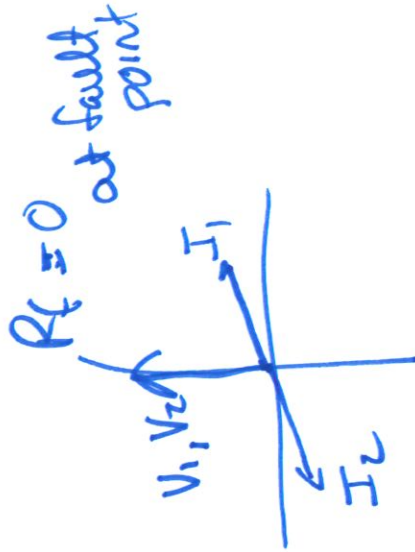
LL



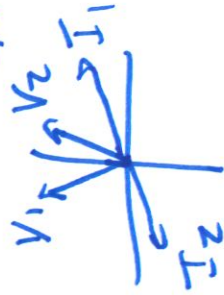
If $R_f = 0$ $V_1 = V_2$ at fault point

$$R_f \neq 0 \quad V_1 \neq V_2 = I_1 R_f$$

$$I_1 = -I_2$$



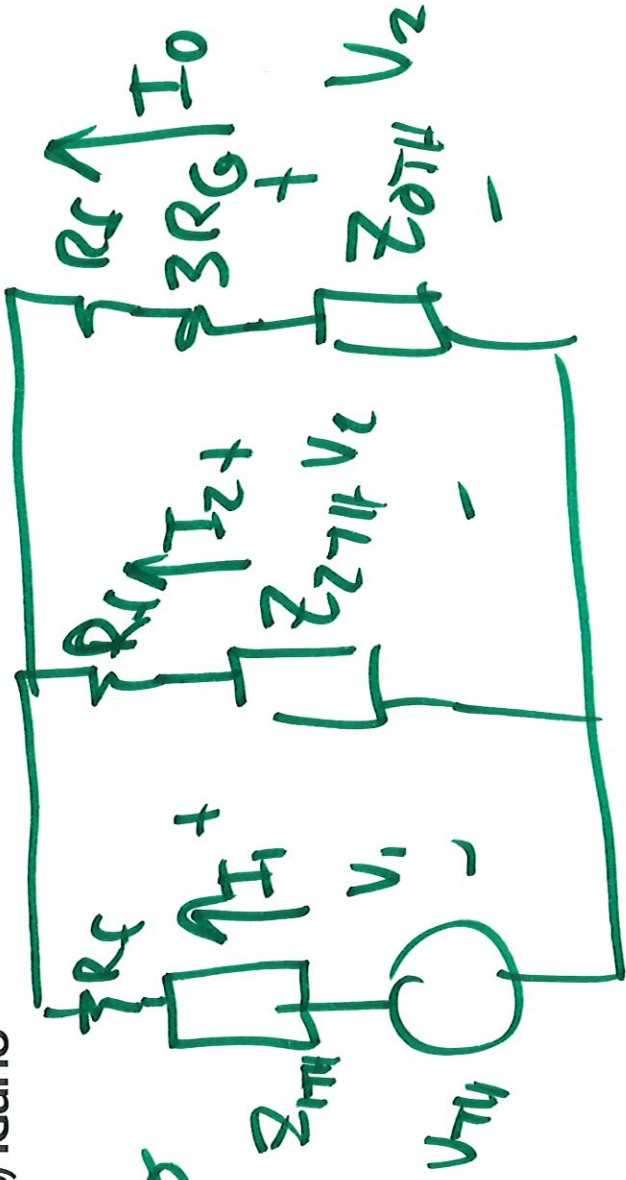
$R_f \neq 0$ at fault point



At bus



DLG



$$I_1 = I_2 + I_0$$

$$\text{If } R_f = R_6 = 0 \quad V_1 = V_2 = V_0 \quad \text{at fault point}$$

Adding Power Flow in Fault Analysis

Important when:

1. Reproducing a field event
2. Studies with larger fault resistance \rightarrow for relay studies

3 for lines that have high

load current

- especially weak system high source impedance ratio ($\frac{Z_s}{Z_{line}}$)

Investigate generator

lower fault currents

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Set line impedance parameters (set zero sequence line impedances to 3 times the positive sequence values):

$$Z_{L23} := j \cdot 0.05 \text{ pu} \quad B_{c23} := 0.005 \cdot \text{pu}$$

$$Z_{L25} := j \cdot 0.35 \text{ pu} \quad B_{c25} := 0.035 \cdot \text{pu}$$

$$Z_{L35} := j \cdot 0.35 \text{ pu} \quad B_{c35} := 0.035 \cdot \text{pu}$$

Transformer 1 Change of base (zero sequence impedances match positive sequence):

$$X_{t11} := 0.1 \cdot \left(\frac{S_B}{200 \text{ MVA}} \right) \quad X_{t10} = 0.05 \cdot \text{pu} \quad X_{t11} := X_{t10}$$

Transformer 2 Change of base (zero sequence impedances match positive sequence):

$$X_{t21} := 0.1 \cdot \left(\frac{S_B}{200 \text{ MVA}} \right) \quad X_{t21} = 0.05 \cdot \text{pu} \quad X_{t20} := X_{t11}$$

A. Assuming the load at Bus 5 is 100MW at 0.9 lagging power factor, perform a power flow solution. Use the voltage at Bus 3 as your angle reference

Options,

- (1) Solve the power flow equations for the entire system using Mathcad solve blocks
- (2) Use Powerworld or a similar load flow problem (at least to check results)

- In order to use V3 as the reference angle, use the angle for V3 from the power flow solution and shift the slack bus angle such that the new angle at Bus 3 is 0.

(1) Solve Full Powerflow Solution Using MathCAD Solve Block

- Positive sequence Y bus for power flow calculations (ignore phase shifts for the moment):

$$Y_{11} := \frac{1}{j \cdot X_{t11}} \quad Y_{12} := \frac{-1}{j \cdot X_{t11}}$$

power flow
YBus → source impedances not included

- Symmetry assumed

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$$Y_{22} := \frac{1}{j \cdot X_{t11}} + \frac{1}{Z_{L23}} + \frac{1}{Z_{L25}} + \frac{j \cdot B_{c23}}{2} + \frac{j \cdot B_{c25}}{2}$$

$$Y_{23} := \frac{-1}{Z_{L23}}$$

$$Y_{25} := \frac{-1}{Z_{L25}}$$

$$Y_{33} := \frac{1}{j \cdot X_{t21}} + \frac{1}{Z_{L23}} + \frac{1}{Z_{L35}} + \frac{j \cdot B_{c23}}{2} + \frac{j \cdot B_{c35}}{2}$$

$$Y_{34} := \frac{-1}{j \cdot X_{t21}}$$

$$Y_{35} := \frac{-1}{Z_{L35}}$$

$$Y_{44} := \frac{1}{j \cdot X_{t11}}$$

$$Y_{55} := \frac{1}{Z_{L25}} + \frac{1}{Z_{L35}} + \left(\frac{j \cdot B_{c25}}{2} + \frac{j \cdot B_{c35}}{2} \right)$$

$$Y_{busPF} := \begin{pmatrix} Y_{11} & Y_{12} & 0 & 0 & 0 \\ Y_{12} & Y_{22} & Y_{23} & 0 & Y_{25} \\ 0 & Y_{23} & Y_{33} & Y_{34} & Y_{35} \\ 0 & 0 & Y_{34} & Y_{44} & 0 \\ 0 & Y_{25} & Y_{35} & 0 & Y_{55} \end{pmatrix}$$

$$Y_{busPF} = \begin{pmatrix} -20i & 20i & 0 & 0 & 0 \\ 20i & -42.8371i & 20i & 0 & 2.8571i \\ 0 & 20i & -42.8371i & 20i & 2.8571i \\ 0 & 0 & 20i & -20i & 0 \\ 0 & 2.8571i & 2.8571i & 0 & -5.6793i \end{pmatrix}$$

Handwritten note: ~~YbusPF~~

$$P2 := 0 \quad P3 := 0 \quad P4 := 0.5pu \quad P5 := -1.0pu$$

$$Q2 := 0 \quad Q3 := 0$$

$$V1 := 1 \quad V4 := 1 \quad a1 := 0$$

$$Q5 := P5 \cdot \tan(\text{acos}(0.9)) \quad Q5 = -0.4843 \cdot pu$$

• Initial guesses

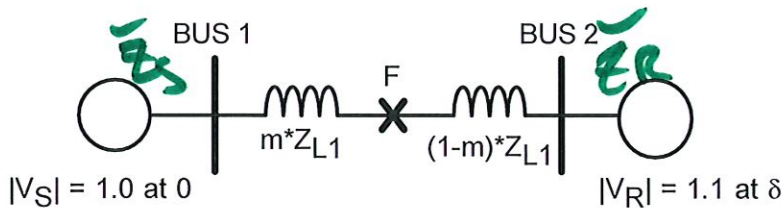
$$V2 := 1 \quad a2 := 0deg$$

$$V3 := 1 \quad a3 := 0deg$$

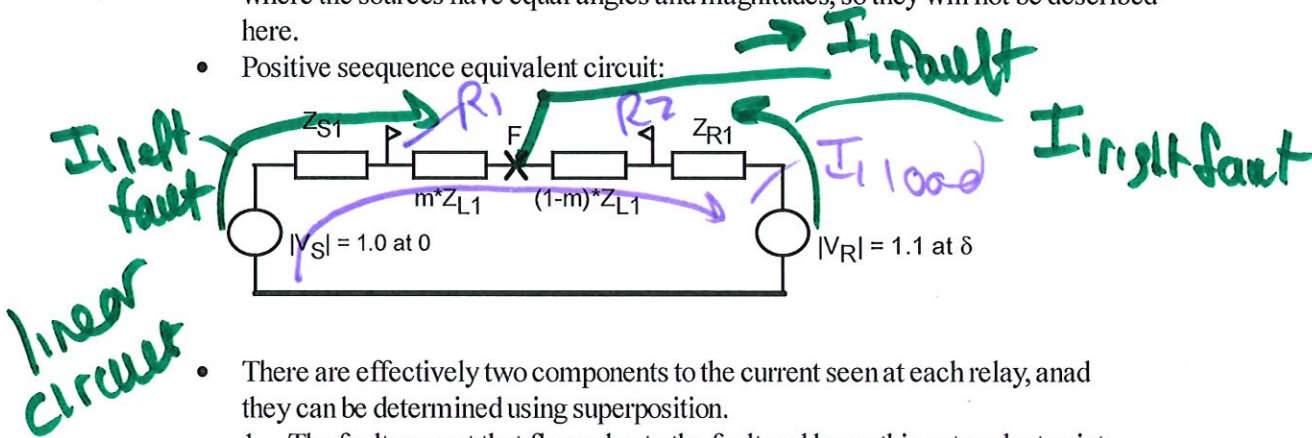
• P5 and Q5 are negative injections since they represent a load

Fault Calculations with Power Flow

- This is much easier to do with Zbus methods. This approach only works for simple systems
- The system below has a pre-fault power flow condition due to the angle and magnitude differences between the sources.
- The fault calculations need to change a little to ensure that the positive sequence current reflects this power flow in the case of a fault where power flow can continue to flow.
- Lets look at a SLG fault case.



- The negative and zero sequence circuits will be the same as one would in a case where the sources have equal angles and magnitudes, so they will not be described here.
- Positive sequence equivalent circuit:



- There are effectively two components to the current seen at each relay, and they can be determined using superposition.
 1. The fault current that flows due to the fault and leave this network at point F and reenters from the neutral plane.
 2. The current that flows between the two sources, the load current.

1. Determining fault current

- We need to find a Thevenin equivalent circuit.
- The process is actually a standard circuit analysis approach (Millman's Theorem), but is typically avoided if the voltage sources are all assumed to have the same magnitude and angle.
 1. Convert the two sources to their Norton equivalents, using the impedance between the source and the fault point. Note that these are phasor calculations.

$$Z_{left1} = Z_{S1} + m \cdot Z_{L1}$$

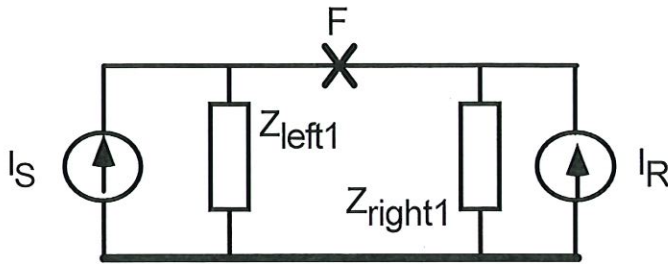
$$Z_{right1} = Z_{R1} + (1 - m) \cdot Z_{L1}$$

$$I_{Norton_left} = \frac{V_{S1}}{Z_{left1}}$$

$$I_{Norton_right} = \frac{V_{S1}}{Z_{right1}}$$



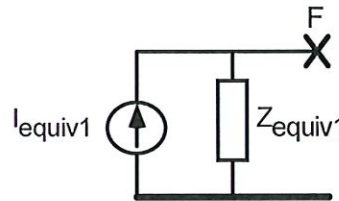
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2. Note that the impedances are in parallel and the current sources are effectively in parallel
- Combine the impedances in parallel
 - Combine the two current sources (note that this is not limited to two sources)

$$Z_{equiv1} = \left(\frac{1}{Z_{left1}} + \frac{1}{Z_{right1}} \right)^{-1}$$

$$I_{equiv1} = I_{Norton_left} + I_{Norton_right}$$

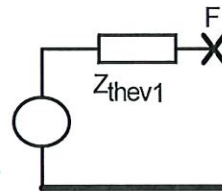


- c. Then convert back to a Thevenin equivalent

$$Z_{thev1} = Z_{equiv1}$$

$$V_{thev1} = I_{equiv1} \cdot Z_{equiv1}$$

voltage at fault point \Rightarrow



- This Thevenin equivalent source is used for the fault calculations. **But not for the power flow calculation**
 - Note that the Thevenin impedance is the same as we always do.
 - Now the voltage source has a magnitude and angle that reflects the difference between the two sources.
 - If the sources both have the same magnitude and angle, the resulting Thevenin voltage source will match that.

2. Determining power flow current

- This is just like any other power flow calculation. In this case you can look between the two known source voltages and the *total impedance* between them. In other cases you might need to find V1 and V2 and just use the line impedance.

$$I_{12} = \frac{V_{S1} - V_{R1}}{Z_{S1} + Z_{L1} + Z_{R1}}$$

$$I_{21} = \frac{V_{R1} - V_{S1}}{(Z_{S1} + Z_{L1} + Z_{R1})}$$

- Notes:
 1. The fault location doesn't matter in this calculation
 2. The Thevenin equivalent source from above is not used
 3. I_{12} flows in the opposite direction I_{21}

3. Total sequence currents

- The positive sequence current for the relay at bus 1 (phasor sums):

$$I_{\text{Relay1}} = I_{f_relay1} + I_{12_relay1}$$

$$I_{\text{Relay2}} = I_{f_relay2} - I_{12_relay1}$$

- I_{f_relay1} and I_{f_relay2} come from current dividers as usual
- The negative and zero sequence currents do not include an load flow current and are simply from current dividers from the fault calculation.

NO load
flow 0 + Z networks

02/01
S17

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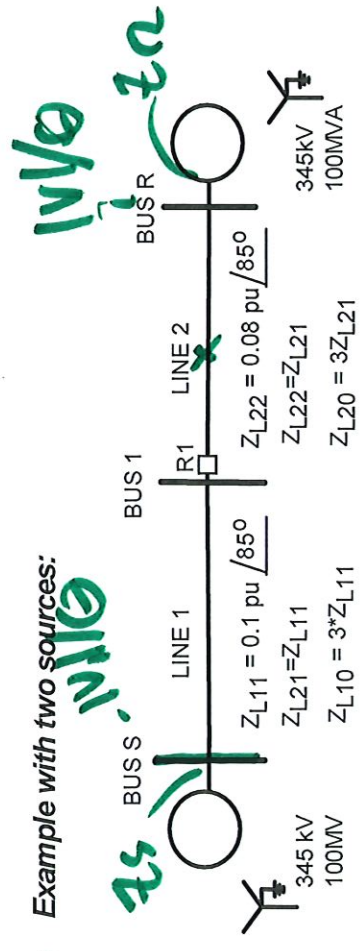
Fault Analysis with Power Flow on the System

pu := 1 MVA := 1000kW

$$a := 1e^{j \cdot 120 \text{deg}}$$

$$A_{012} := \begin{pmatrix} 1 & 1 & 1 \\ 1 & a^2 & a \\ 1 & a & a^2 \end{pmatrix}$$

• Example with two sources:



$V_S = 1.0 \text{ pu @ } 0 \text{ deg}$
 $Z_{S1} = j0.03 \text{ pu}$
 $Z_{S2} = Z_{S1}$
 $Z_{S0} = 3 \cdot Z_{S1}$

Per unit line impedances calculated with SB=100MVA and VB=345KV LL

$Z_{L11} = 0.1 \text{ pu} \angle 85^\circ$
 $Z_{L21} = Z_{L11}$
 $Z_{L10} = 3 \cdot Z_{L11}$

$Z_{S1} := j \cdot 0.03 \text{ pu}$
 $Z_{S2} := Z_{S1}$
 $Z_{S0} := 3Z_{S1}$
 $Z_{R1} := j \cdot 0.06 \text{ pu}$
 $Z_{R2} := Z_{R1}$
 $Z_{R0} := 3Z_{R1}$

$Z_{L11} := 0.1 \text{ pu} \cdot e^{j \cdot 85 \text{deg}}$
 $Z_{L10} = 0.01 + 0.1i$
 $Z_{L12} := Z_{L11}$

$Z_{L21} := 0.08 \text{ pu} \cdot e^{j \cdot 85 \text{deg}}$
 $Z_{L20} = 0.01 + 0.08i$
 $Z_{L22} := Z_{L21}$

$Z_{L20} := 3 \cdot Z_{L21}$
 $Z_{L20} = 0.02 + 0.24i$

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1.065 r.g.W

- For faults on Line 2:

$$Z_{L2_1_thev}(n) := \left[\frac{1}{Z_{S1} + Z_{L11} + n \cdot Z_{L21}} + \frac{1}{(1-n) \cdot Z_{L21} + Z_{R1}} \right]^{-1}$$

$$Z_{L2_2_thev}(n) := \left[\frac{1}{Z_{S2} + Z_{L12} + n \cdot Z_{L22}} + \frac{1}{(1-n) \cdot Z_{L22} + Z_{R2}} \right]^{-1}$$

$$Z_{L2_0_thev}(n) := \left[\frac{1}{Z_{S0} + Z_{L10} + n \cdot Z_{L20}} + \frac{1}{(1-n) \cdot Z_{L20} + Z_{R0}} \right]^{-1}$$

Impedance Matrix Approach

- Need positive, negative and zero sequence matrices

$$Y_{bus1}(m) := \begin{bmatrix} \frac{1}{Z_{S1}} + \frac{1}{Z_{L11}} & \frac{-1}{Z_{L11}} & 0 & 0 \\ \frac{-1}{Z_{L11}} & \frac{1}{Z_{L11}} + \frac{1}{m \cdot Z_{L21}} & 0 & \frac{-1}{m \cdot Z_{L21}} \\ 0 & 0 & \frac{1}{(1-m) \cdot Z_{L21}} + \frac{1}{Z_{R1}} & \frac{-1}{(1-m) \cdot Z_{L21}} \\ 0 & \frac{-1}{m \cdot Z_{L21}} & \frac{-1}{(1-m) \cdot Z_{L21}} & \frac{1}{m \cdot Z_{L21}} + \frac{1}{(1-m) \cdot Z_{L21}} \end{bmatrix}$$

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or dependent
Y BUS 0, 1, 2

$$Z_{bus1}(m) := Y_{bus1}(m)^{-1}$$

$$Y_{bus2}(m) := \begin{bmatrix} \frac{1}{Z_{S2}} + \frac{1}{Z_{L12}} & -\frac{1}{Z_{L12}} & 0 & 0 \\ -\frac{1}{Z_{L12}} & \frac{1}{Z_{L12}} + \frac{1}{m \cdot Z_{L22}} & 0 & -\frac{1}{m \cdot Z_{L22}} \\ 0 & 0 & \frac{1}{(1-m) \cdot Z_{L22}} + \frac{1}{Z_{R2}} & -\frac{1}{(1-m) \cdot Z_{L22}} \\ 0 & -\frac{1}{m \cdot Z_{L22}} & \frac{-1}{(1-m) \cdot Z_{L22}} & \frac{1}{m \cdot Z_{L22}} + \frac{1}{(1-m) \cdot Z_{L22}} \end{bmatrix}$$

$$Z_{bus2}(m) := Y_{bus2}(m)^{-1}$$

$$Y_{bus0}(m) := \begin{bmatrix} \frac{1}{Z_{S0}} + \frac{1}{Z_{L10}} & -\frac{1}{Z_{L10}} & 0 & 0 \\ -\frac{1}{Z_{L10}} & \frac{1}{Z_{L10}} + \frac{1}{m \cdot Z_{L20}} & 0 & -\frac{1}{m \cdot Z_{L20}} \\ 0 & 0 & \frac{1}{(1-m) \cdot Z_{L20}} + \frac{1}{Z_{R0}} & -\frac{1}{(1-m) \cdot Z_{L20}} \\ 0 & -\frac{1}{m \cdot Z_{L20}} & \frac{-1}{(1-m) \cdot Z_{L20}} & \frac{1}{m \cdot Z_{L20}} + \frac{1}{(1-m) \cdot Z_{L20}} \end{bmatrix}$$

$$Z_{bus0}(m) := Y_{bus0}(m)^{-1}$$

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- SLG Fault

$$I_{f0}(m) := \frac{V_{1_Thev}(m)}{Z_{L2_1_thev}(m) + Z_{L2_2_thev}(m) + Z_{L2_0_thev}(m)}$$

$$I_{f1}(m) := I_{f0}(m)$$

$$I_{f2}(m) := I_{f0}(m)$$

$$|I_{f0}(0.5)| = 3.22 \cdot pu$$

$$\arg(I_{f0}(0.5)) = -95.09 \cdot deg$$

- Fault Currents at Relay 1:

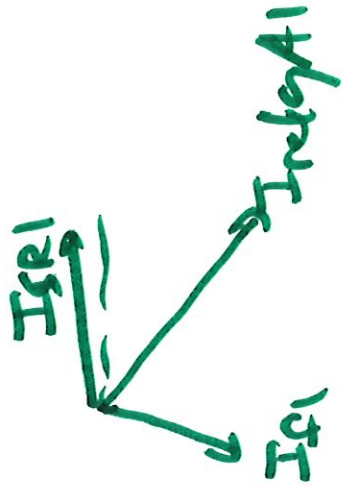
$$I_{fA1}(m) := I_{f1}(m) \cdot \left[\frac{Z_{R1} + (1 - m) \cdot Z_{L21}}{(Z_{S1} + Z_{L11} + m \cdot Z_{L21}) + [Z_{R1} + (1 - m) \cdot Z_{L21}]} \right]$$

$$|I_{fA1}(0.5)| = 1.19 \quad \arg(I_{fA1}(0.5)) = -93.76 \cdot deg$$

load flow

However, the positive sequence current seen by the relay will include the load current

$$I_{relayA1}(m) := I_{fA1}(m) + I_{SR1}$$



$$I_{relayA1}(0.5) = 0.91 - 1.08i$$

$$|I_{relayA1}(0.5)| = 1.41$$

$$\arg(I_{relayA1}(0.5)) = -49.96 \cdot deg$$

Negative sequence and zero sequence currents don't see load current..

$$I_{relayA2}(m) := I_{f2}(m) \cdot \left[\frac{(1 - m) \cdot Z_{L22} + Z_{R2}}{(Z_{S2} + Z_{L12} + m \cdot Z_{L22}) + [Z_{R2} + (1 - m) \cdot Z_{L22}]} \right]$$

$$|I_{relayA2}(0.5)| = 1.19$$

$$\arg(I_{relayA2}(0.5)) = -93.76 \cdot deg$$

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Now add power flow based on phase angle differences

- Make Bus S the slack bus at 1.0pu
- Set Bus R magnitude and angle

$$V_{S1} := 1.0 \text{pu} e^{j \cdot 0 \text{deg}} \quad V_{R1} := 1.02 \text{pu} e^{-j \cdot 10.074 \text{deg}}$$

- This case is simple enough that we don't need to do a normal power flow solution.

$$I_{SR1} := \frac{V_{S1} - V_{R1}}{Z_{L11} + Z_{L21}} \quad |I_{SR1}| = 0.99 \text{pu} \quad \arg(I_{SR1}) = 6.37 \text{deg}$$

$$V_{B1} := V_{S1} - I_{SR1} \cdot Z_{L11} \quad |V_{B1}| = 1.01 \text{pu} \quad \arg(V_{B1}) = -5.65 \text{deg}$$



- But for fault analysis we need the voltages behind the source impedances

$$V_{src_S} := V_{S1} + I_{SR1} \cdot Z_{S1} \quad |V_{src_S}| = 0.997 \quad \arg(V_{src_S}) = 1.7 \text{deg}$$

$$V_{src_R} := V_{R1} - I_{SR1} \cdot Z_{R1} \quad |V_{src_R}| = 1.038 \quad \arg(V_{src_R}) = -13.22 \text{deg}$$

$$I_{sINor}(m) := \frac{V_{src_S}}{Z_{S1} + Z_{L11} + m \cdot Z_{L21}} \quad I_{rINor}(m) := \frac{V_{src_R}}{Z_{R1} + (1 - m) \cdot Z_{L21}}$$

$$I_{1_Nor}(m) := I_{sINor}(m) + I_{rINor}(m)$$

$$V_{1_Thev}(m) := I_{1_Nor}(m) \cdot Z_{L2_1_thev}(m) \quad |V_{1_Thev}(0.5)| = 1.01 \text{pu} \quad \arg(V_{1_Thev}(0.5)) = -7.87 \text{deg}$$

at fault point
 $n = 0.5$

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$$I_{\text{relayA0}}(m) := I_{f0}(m) \cdot \left[\frac{(1-m) \cdot Z_{L20} + Z_{R0}}{Z_{S0} + Z_{L10} + m \cdot Z_{L20} + [(1-m) \cdot Z_{L20} + Z_{R0}]} \right]$$

$$|I_{\text{relayA0}}(0.5)| = 1.19 \quad \arg(I_{\text{relayA0}}(0.5)) = -93.76 \cdot \text{deg}$$

$$V_{\text{relayA1}}(m) := V_{\text{src}_S} - I_{\text{relayA1}}(m) \cdot (Z_{S1} + Z_{L11}) \quad |V_{\text{relayA1}}(0.5)| = 0.85 \cdot \text{pu}$$

$$\arg(V_{\text{relayA1}}(0.5)) = -5.29 \cdot \text{deg}$$

$$V_{\text{relayA2}}(m) := -I_{\text{relayA2}}(m) \cdot (Z_{S2} + Z_{L12}) \quad |V_{\text{relayA2}}(0.5)| = 0.15 \cdot \text{pu}$$

$$\arg(V_{\text{relayA2}}(0.5)) = 172.4 \cdot \text{deg}$$

$$V_{\text{relayA0}}(m) := -I_{\text{relayA0}}(m) \cdot (Z_{S0} + Z_{L10}) \quad |V_{\text{relayA0}}(0.5)| = 0.46 \cdot \text{pu}$$

$$\arg(V_{\text{relayA0}}(0.5)) = 172.4 \cdot \text{deg}$$

$$I_{\text{ABC_RA}}(m) := A_{012} \cdot \begin{pmatrix} I_{\text{relayA0}}(m) \\ I_{\text{relayA1}}(m) \\ I_{\text{relayA2}}(m) \end{pmatrix}$$

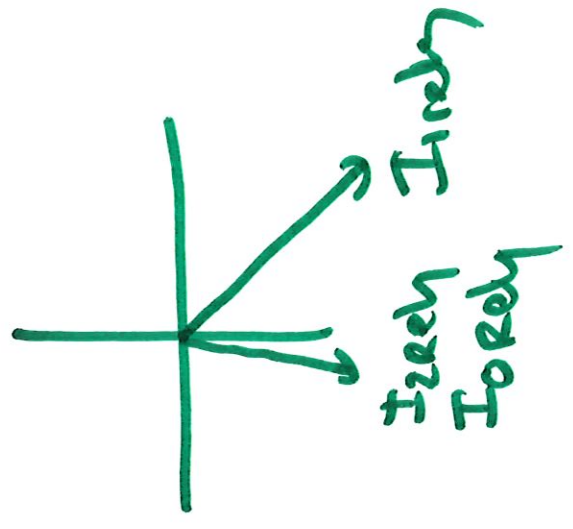
$$V_{\text{ABC_RA}}(m) := A_{012} \cdot \begin{pmatrix} V_{\text{relayA0}}(m) \\ V_{\text{relayA1}}(m) \\ V_{\text{relayA2}}(m) \end{pmatrix}$$

$$|I_{\text{ABC_RA}}(0.5)| = \begin{pmatrix} 3.54 \\ 0.99 \cdot \text{pu} \\ 0.99 \end{pmatrix}$$

1000 current

$$\arg(I_{\text{ABC_RA}}(0.5)) = \begin{pmatrix} -77.75 \\ -113.63 \text{ deg} \\ 126.37 \end{pmatrix}$$

essence of fault



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$$\overrightarrow{|V_{ABC_RA}(0.5)|} = \begin{pmatrix} 0.23 \\ 1.18 \cdot pu \\ 1.2 \end{pmatrix}$$

$$\overrightarrow{\arg(V_{ABC_RA}(0.5))} = \begin{pmatrix} 0.82 \\ -138.99 \cdot deg \\ 127 \end{pmatrix}$$

Without load flow:

$$I_A := 3.83 pu \cdot e^{-j \cdot 85.88 deg}$$

$$I_B := 0$$

$$I_C := 0$$

Now repeat using Zbus:

$$I_{0_SLG(m)} := \frac{V_{1_Thev(m)}}{Z_{bus1(m)}_{3,3} + Z_{bus2(m)}_{3,3} + Z_{bus0(m)}_{3,3}} \quad I_{1_SLG(m)} := I_{0_SLG(m)}$$

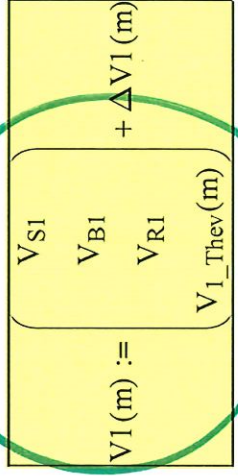
$$I_{2_SLG(m)} := I_{0_SLG(m)} \quad |I_{0_SLG(0.5)}| = 3.22 \quad \arg(I_{0_SLG(0.5)}) = -95.09 \cdot deg$$

$$I_{ABC_SLG(m)} := A_{012} \cdot \begin{pmatrix} I_{0_SLG(m)} \\ I_{1_SLG(m)} \\ I_{2_SLG(m)} \end{pmatrix} \quad \overrightarrow{|I_{ABC_SLG(0.5)}|} = \begin{pmatrix} 9.66 \\ 0 \\ 0 \end{pmatrix} \cdot pu \quad \overrightarrow{\arg(I_{ABC_SLG(0.5)})} = \begin{pmatrix} -95.09 \\ 19.98 \cdot deg \\ 19.98 \end{pmatrix}$$

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- Now find the voltages:

$$\Delta V1(m) := Z_{bus1}(m) \cdot \begin{pmatrix} 0 \\ 0 \\ 0 \\ -I1_SLG(m) \end{pmatrix}$$



how we put in fault load flow

$$\Delta V2(m) := Z_{bus2}(m) \cdot \begin{pmatrix} 0 \\ 0 \\ 0 \\ -I2_SLG(m) \end{pmatrix}$$

$$V2(m) := \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \Delta V2(m)$$

$$\Delta V0(m) := Z_{bus0}(m) \cdot \begin{pmatrix} 0 \\ 0 \\ 0 \\ -I0_SLG(m) \end{pmatrix}$$

$$V0(m) := \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix} + \Delta V0(m)$$

- Relay 1 voltage:

$$V_{ABC_B1}(m) := A_{012} \cdot \begin{pmatrix} V0(m)1 \\ V1(m)1 \\ V2(m)1 \end{pmatrix}$$

$$|V_{ABC_B1}(0.5)| = \begin{pmatrix} 0.23 \\ 1.18 \\ 1.2 \end{pmatrix} \cdot pu$$

$$\arg(V_{ABC_B1}(0.5)) = \begin{pmatrix} 0.82 \\ -138.99 \\ 127 \end{pmatrix} \cdot deg$$

solution comes from
 to calc
 - don't need source
 in internal voltage

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Same as above....

don't need to add I_{1F} + I_{2F}

- Relay 1 current:

$$I_{B1_F_1}(m) := \frac{V1(m)_1 - V1(m)_3}{m \cdot Z_{L21}}$$

$$\arg(I_{B1_F_1}(0.5)) = -49.96 \cdot \text{deg}$$

$$|I_{B1_F_1}(0.5)| = 1.41$$

$$I_{B1_F_2}(m) := \frac{V2(m)_1 - V2(m)_3}{m \cdot Z_{L22}}$$

$$\arg(I_{B1_F_2}(0.5)) = -93.76 \cdot \text{deg}$$

$$|I_{B1_F_2}(0.5)| = 1.19$$

$$I_{B1_F_0}(m) := \frac{V0(m)_1 - V0(m)_3}{m \cdot Z_{L20}}$$

$$\arg(I_{B1_F_0}(0.5)) = -93.76 \cdot \text{deg}$$

$$|I_{B1_F_0}(0.5)| = 1.19$$

$$I_{ABC_R1}(m) := A_{012} \cdot \begin{pmatrix} I_{B1_F_0}(m) \\ I_{B1_F_1}(m) \\ I_{B1_F_2}(m) \end{pmatrix}$$

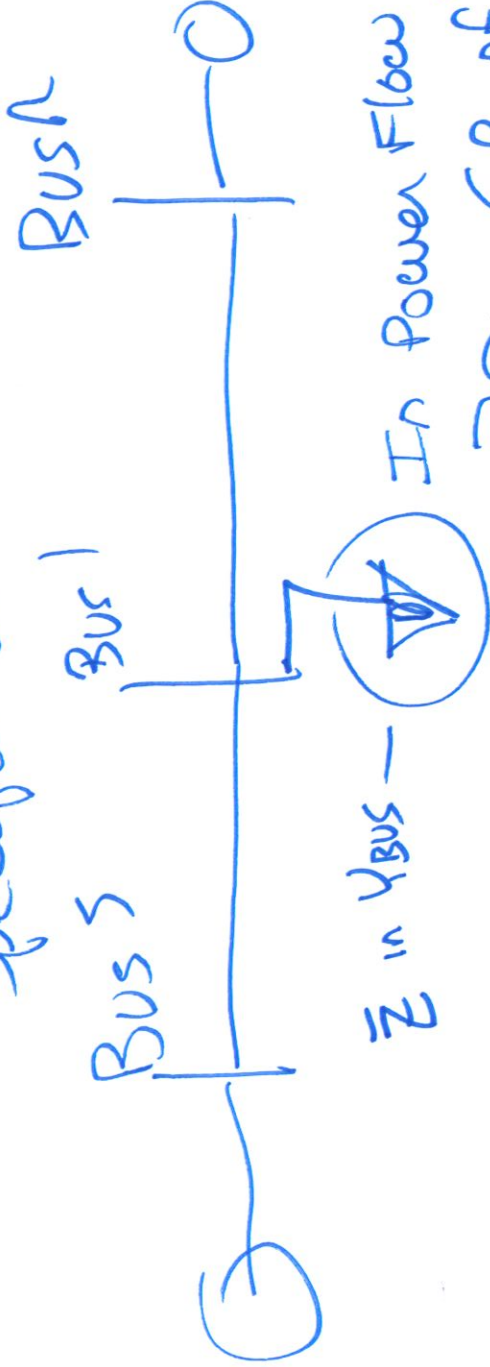
$$\overrightarrow{|I_{ABC_R1}(0.5)|} = \begin{pmatrix} 3.54 \\ 0.99 \cdot \text{pu} \\ 0.99 \end{pmatrix}$$

$$\overrightarrow{\arg(I_{ABC_R1}(0.5))} = \begin{pmatrix} -77.75 \\ -113.63 \cdot \text{deg} \\ 126.37 \end{pmatrix}$$

Same as above....

Next Time

We will add load at a specific bus



$$S = V \cdot I^*$$

$$P_u = V \cdot \frac{V^*}{Z} = \frac{|V|^2}{Z}$$

- constant P
 - constant I
 - constant Z
 - motor
- How does P, Q vary with |V| at bus