

ECE 523
Symmetrical Components

Session 20

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ECE 523
Lecture 19

EMTP Variants

- Original version mainly modeled RLC elements switches, ideal sources and lines
- Many extensions and several versions
 - » ATP: Alternate transients program (<http://www.emtp.org>)
 - » EMTP-RV (<http://www.emtp.com>) latest from DCG
 - » EMTDC: student version available free from their web site (<http://www.pscad.com/>)
 - » RTDS: Real time digital simulator (cost)
 - » SimPowerSystems blockset for Matlab

Intro to EMTP simulation 7 Fall 2023

HyperSim (Opal-RT)

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Using EMT Programs

- Outputs are voltage, current, power, and energy versus time
- Control variables are available if controls are modeled
- Can model simple controls using EMTs control models or can interface to FORTRAN (in some cases C or Matlab too)
 - » Programs have internal control modeling
 - » Graphical user interface

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U I	The ATP Version	ECE 523 Lecture 19
		<ul style="list-style-type: none">• ATP is essentially free. A license application needs to be filled out (do not choose student license)<ul style="list-style-type: none">» https://www.atp-empt.org/» The purpose is to limit access to parties that have participated in "EMTP-Commerce"
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U I	ATPDraw	ECE 523 Lecture 19
		<ul style="list-style-type: none">• Available for download from ATP distribution sites• Follow link for ATPDraw for information about the program<ul style="list-style-type: none">» Latest versions are version 7.4» File format not backward compatible» http://www.atpdraw.net/ (ATPDraw only, not ATP itself)• Get the program and the patch files (update to fix bugs in executable)• Manual and introduction presentation for download
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U I	PSCAD/EMTDC	ECE 523 Lecture 19
		<ul style="list-style-type: none">• Education version available in ECE labs• Free Student Edition (15 node limit)<ul style="list-style-type: none">» Go to: http://www.pscad.com/» Create account and get set up to download<ul style="list-style-type: none">– Download the Program itself– Includes free Fortran Compiler<ul style="list-style-type: none">□ Need unless you have compatible one installed• Website also has tutorials• Remote access on UI computers
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U I	EMTP-RV	ECE 523 Lecture 19
		<ul style="list-style-type: none">• Available in ECE labs• Remotely available on University of Idaho computers• Tutorials available at https://www.emtp-software.com/
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Validation of Models... and Results

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- Need to have a basic idea of what the transient response should look like
- Test your system with some very predictable cases
- Start from steady-state operating point
- Understanding behavior will be one of the focuses of this course

Intro to EMTP simulation

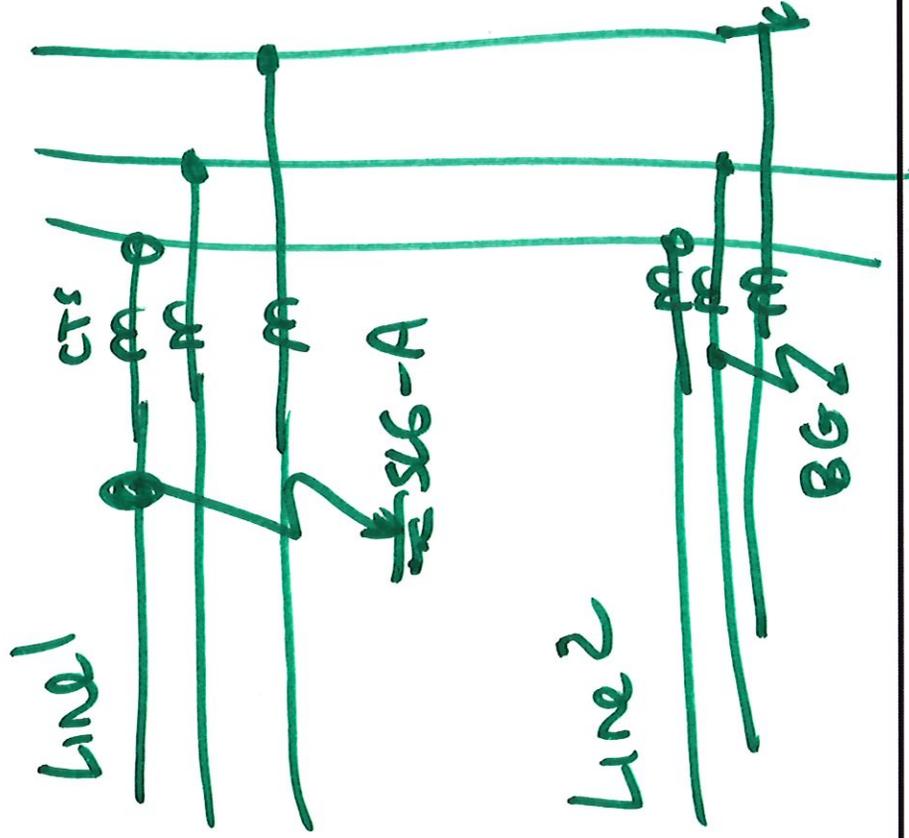
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Simultaneous Faults

- Almost all faults are a single event at a single location



→ two close together faults on different lines

- faults not on system very long

- sometimes two faults are present at same time

that are ~~not~~ unrelated

- or related - for example

• a fault that has a broken conductor → that falls to the ground

Analysis of Simultaneous Faults

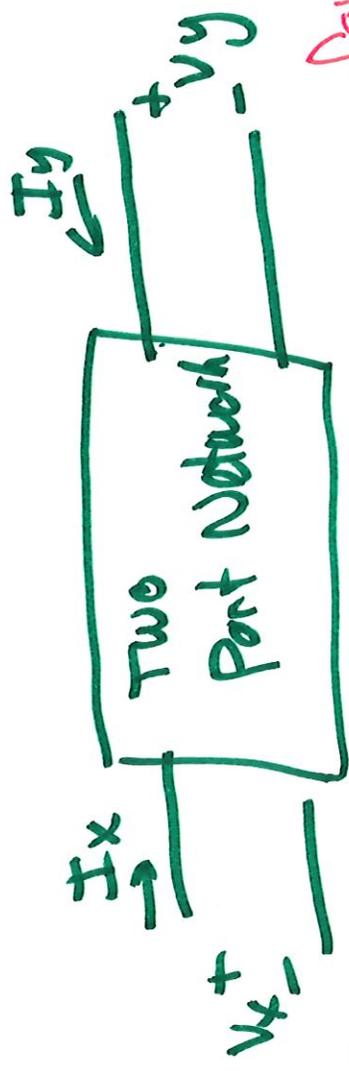
- for faults at one location
or different locations
- 2 part Thevenin Equivalent
 - looking between locations
- we also need to translate
between symmetrical component
reference frames in some cases.

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for example

- AG fault at one location \rightarrow A ref components
- and BG at another one - B ref components

Two Port Networks



fault at y

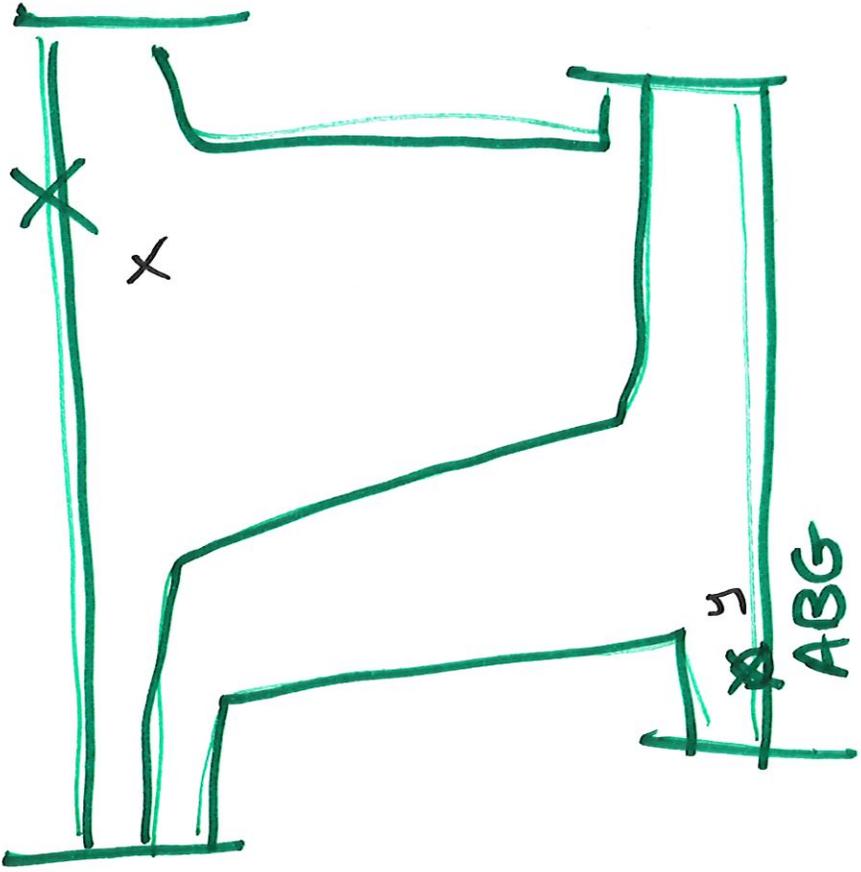
fault at x

Equivalent

Pos } 3 networks
neg }
Zero }

connectors & P_{in}
between systems
power system

SLG-A



- Three types of two port networks for circuit analysis (Section 9.1 + 9.2 in Anderson book)

1. Impedance type (Z-type)

$$\begin{bmatrix} V_{x_{01z}} \\ V_{y_{01z}} \end{bmatrix} = \begin{bmatrix} Z_{xx_{01z}} & Z_{xy_{01z}} \\ Z_{yx_{01z}} & Z_{yy_{01z}} \end{bmatrix} \begin{bmatrix} I_{x_{01z}} \\ I_{y_{01z}} \end{bmatrix}$$

→ 3 - one each for pos. neg, zero

2. Admittance (Y-type)

$$\begin{bmatrix} I_x \\ I_y \end{bmatrix} = \begin{bmatrix} Y_{xx} & Y_{xy} \\ Y_{yx} & Y_{yy} \end{bmatrix} \begin{bmatrix} V_x \\ V_y \end{bmatrix}$$

3. Hybrid → H-type (H-parameters)

$$\begin{bmatrix} V_x \\ I_y \end{bmatrix} = \begin{bmatrix} H_{xx} & H_{xy} \\ H_{yx} & H_{yy} \end{bmatrix} \begin{bmatrix} I_x \\ V_y \end{bmatrix}$$

→ Some work better series faults
others for shunts

→ Also voltage source versus current source

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Example : Fault X is SLG on phase A

fault Y is BC fault

SLG on A

- A neg components

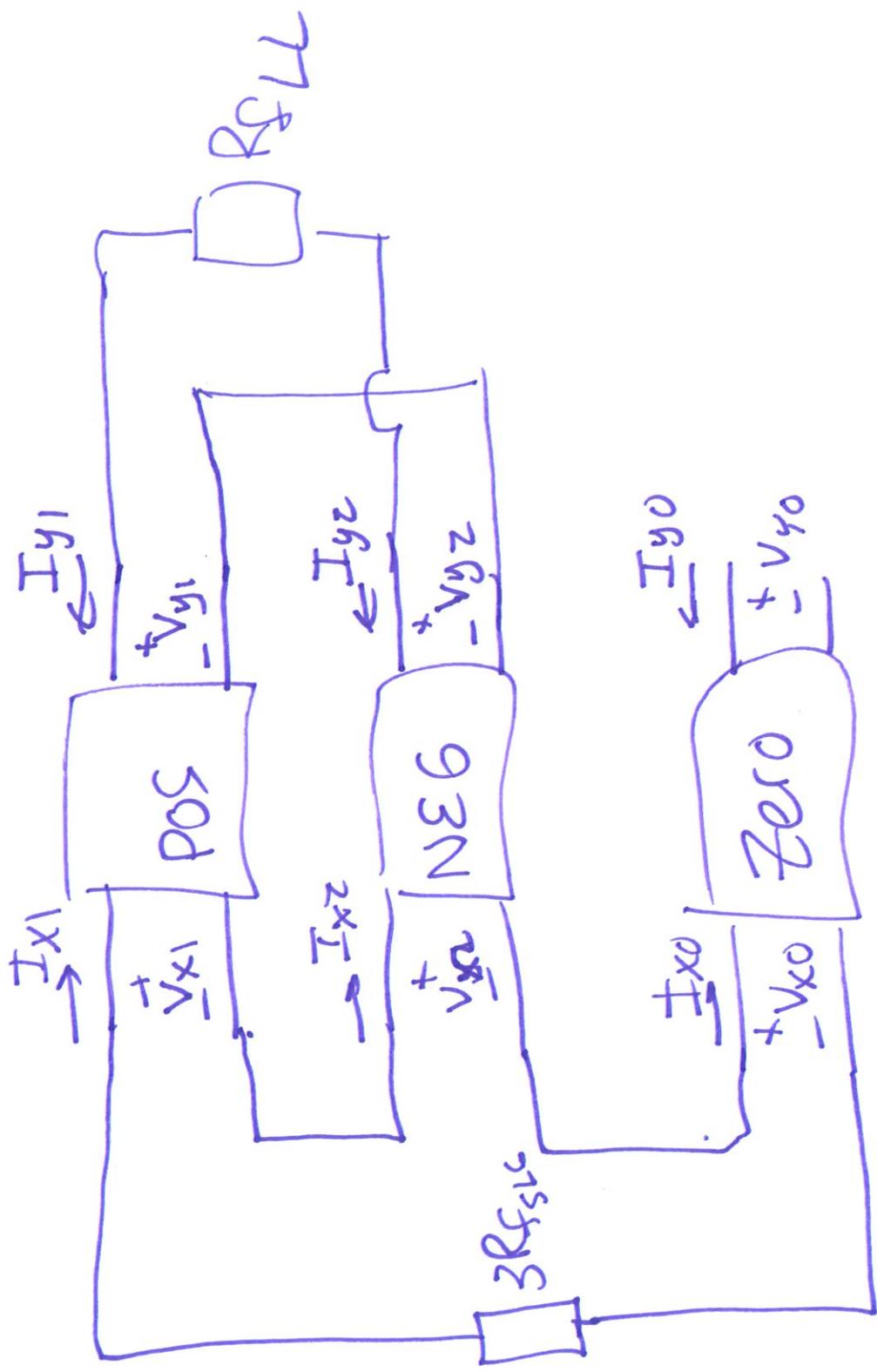
$I_0 = I_1 = I_2$ at fault locat-

$V_0 + V_1 + V_2 = 3I_0 R_f$

BC $I_1 = -I_2$

$V_1 - V_2 = I_1 R_f$

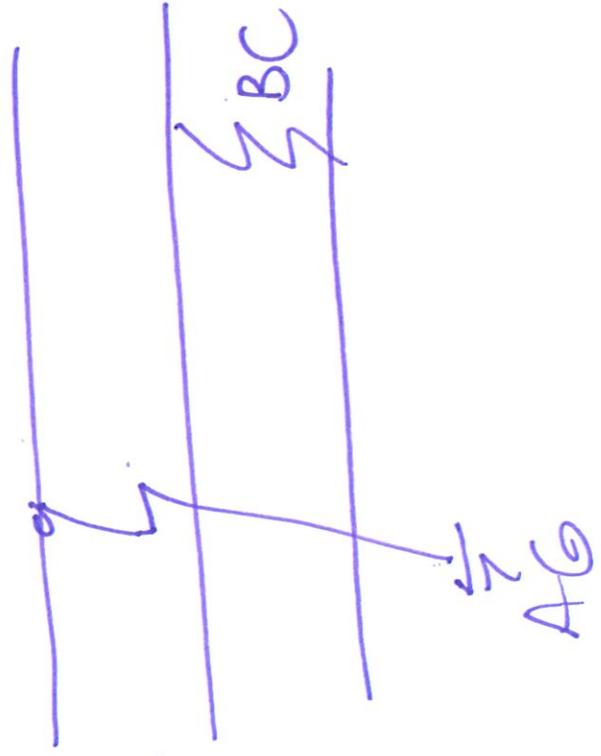
A neg components



Suppose the LL fault is AB fault \rightarrow C neg components



Example → AG & BC
 at same location



ABC constraints

$$SLG: V_{AG} = R_{AG} I_{AG}$$

$$LC \quad I_{BF} = -I_{CF}$$

$$V_{BG} = V_{CG} + R_C I_{BF}$$

$$\begin{bmatrix} I_0 \\ I_1 \\ I_2 \end{bmatrix} = A_{012}^{-1} \begin{bmatrix} I_{Ae} \\ I_{Bf} \\ I_{Cc} \end{bmatrix}$$

~~I_{Bf}~~

$$I_0 = \frac{1}{3} [I_{Ae} + I_{Bf} - I_{Bf}] = \frac{I_{Ae}}{3}$$

$$I_1 = \frac{1}{3} [I_{Ae} + a I_{Bf} - a^2 I_{Bf}]$$

$$I_2 = \frac{1}{3} [I_{Ae} + a^2 I_{Bf} - a I_{Bf}]$$

$$I_1 + I_2 = \frac{1}{3} \left[2 I_{Af} + B_f \left[a - a^2 + 0^2 - a \right] \right]$$

$$I_1 + I_2 = \frac{2}{3} I_{Af} = 2 I_0$$

$$V_{AG} = R_G I_{Af}$$

$$V_{BG} = V_{CG} + R_{fBC} \cdot I_{Bf}$$

for the moment let $R_G = R_{fBC} = 0$

$$V_{AG} = 0 = V_{A0} + V_{A1} + V_{A2}$$

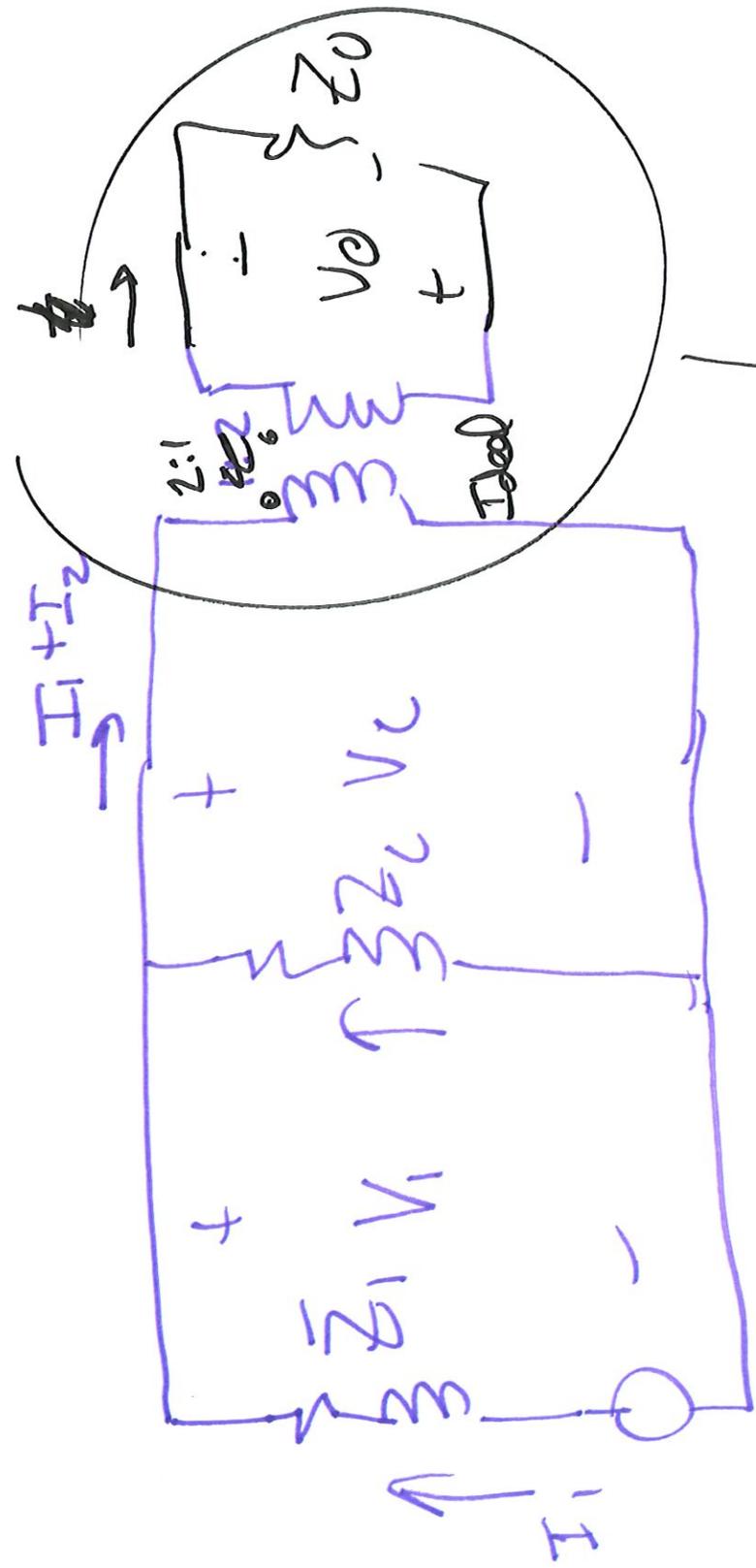
$$V_{BG} = V_{CG} \Rightarrow V_{A1} = V_{A2}$$

Then $V_{AG} = 0 = V_{A0} + V_{A1} + V_{A2}$

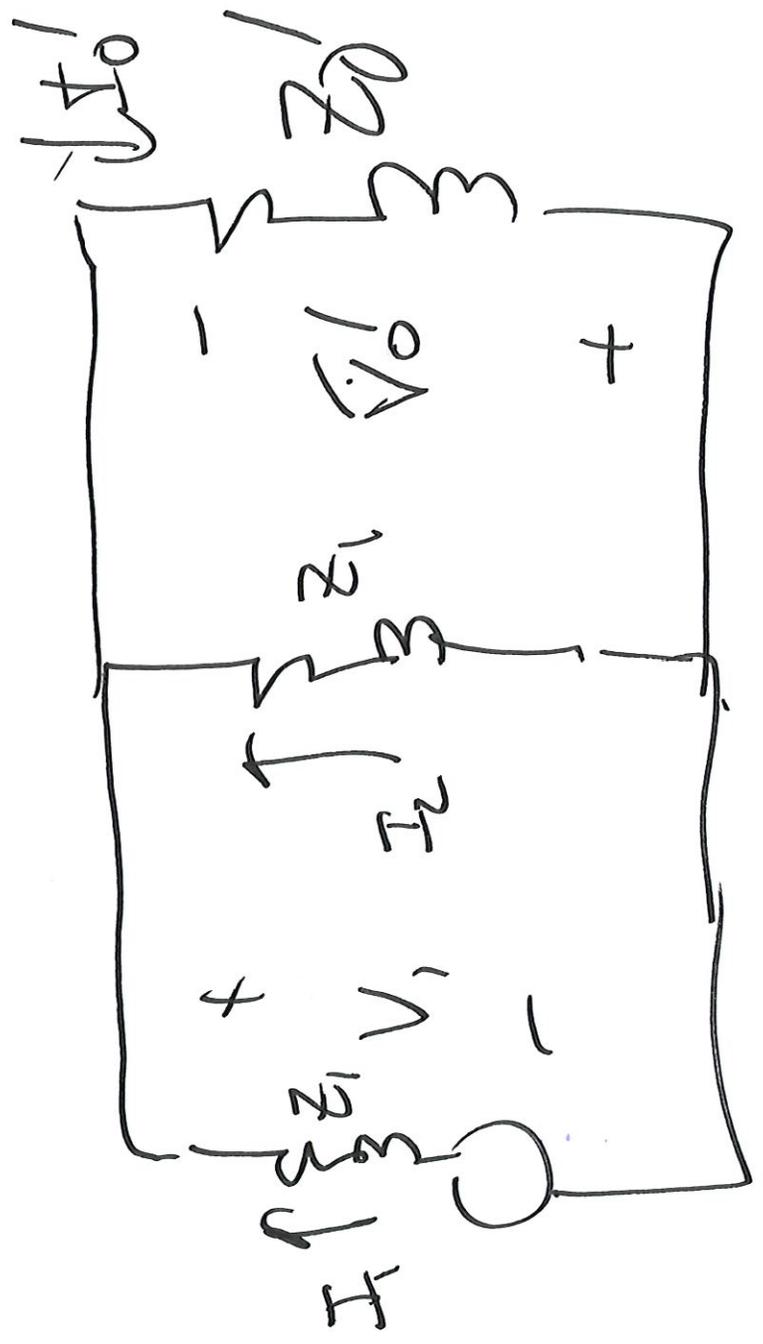
$$0 = V_{A0} + 2V_{A1} = V_{A0} + 2V_{A2}$$

$$V_{A1} = V_{A2} = -\frac{V_{A0}}{2}$$

Since same location we can use a single port equivalent



refer across transformer



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$$Y_{Bus0}(M) := \begin{bmatrix} \frac{1}{Z_{S0}} & 0 & 0 & 0 & 0 \\ 0 & \frac{1}{Z_{T10}} + \frac{1}{M \cdot Z_{L0}} & 0 & 0 & \frac{-1}{M \cdot Z_{L0}} \\ 0 & 0 & \frac{1}{(1-M) \cdot Z_{L0}} + \frac{1}{Z_{T20}} & 0 & \frac{-1}{(1-M) \cdot Z_{L0}} \\ 0 & 0 & 0 & \frac{1}{Z_{R0}} & 0 \\ 0 & \frac{-1}{M \cdot Z_{L0}} & \frac{-1}{(1-M) \cdot Z_{L0}} & 0 & \frac{1}{M \cdot Z_{L0}} + \frac{1}{(1-M) \cdot Z_{L0}} \end{bmatrix}$$

$$Z_{Bus1}(M) := Y_{Bus1}(M)^{-1}$$

$$Z_{Bus2}(M) := Y_{Bus2}(M)^{-1}$$

$$Z_{Bus0}(M) := Y_{Bus0}(M)^{-1}$$

Simultaneous AG and BC faults 30% of the way from Bus 1 to Bus 2

$$I_1 + I_2 = 2 \cdot I_0$$

$$V_1 = V_2 = \frac{-1}{2} \cdot V_0$$

$$V_f := 1.0 \text{ pu} \quad \text{No load}$$

$$M := 0.3$$

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$$I_1 := \frac{V_f}{Z_{Bus1}(M)_{4,4} + \left[\frac{1}{Z_{Bus2}(M)_{4,4}} + \frac{1}{(Z_{Bus0}(M)_{4,4}) \cdot \frac{1}{4}} \right]^{-1}}$$

$|I_1| = 2.055 \cdot pu$ $\arg(I_1) = -86.871 \cdot deg$

$$I_2 := -I_1 \cdot \left[\frac{(Z_{Bus0}(M)_{4,4})}{4} + \frac{(Z_{Bus2}(M)_{4,4})}{4} \right]$$

$|I_2| = 0.55 \cdot pu$ $\arg(I_2) = 91.613 \cdot deg$

$$I_0 := \frac{I_1}{2} \cdot \left[\frac{Z_{Bus2}(M)_{4,4}}{Z_{Bus2}(M)_{4,4} + \frac{(Z_{Bus0}(M)_{4,4})}{4}} + \frac{Z_{Bus2}(M)_{4,4}}{(Z_{Bus0}(M)_{4,4}) \cdot \frac{1}{4}} \right]$$

$|I_0| = 0.752 \cdot pu$ $\arg(I_0) = -86.316 \cdot deg$

Handwritten notes:
 → correct for my current constraints
 $(I_1 + I_2) - 2 \cdot I_0 = 0$

$$V_1 := V_f - I_1 \cdot Z_{Bus1}(M)_{4,4}$$

$|V_1| = 0.211 \cdot pu$ $\arg(V_1) = -1.196 \cdot deg$

$$V_2 := -I_2 \cdot Z_{Bus2}(M)_{4,4}$$

$|V_2| = 0.211 \cdot pu$ $\arg(V_2) = -1.196 \cdot deg$

$$V_0 := -I_0 \cdot Z_{Bus0}(M)_{4,4}$$

$|V_0| = 0.423 \cdot pu$ $\arg(V_0) = 178.804 \cdot deg$

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$$\frac{-V_0}{2} - V_1 = 0$$

$$V_{ABC} := A_{012} \cdot \begin{pmatrix} V_0 \\ V_1 \\ V_2 \end{pmatrix} \quad \vec{V}_{ABC} = \begin{pmatrix} 0 \\ 0.634 \\ 0.634 \end{pmatrix}$$

$$\arg(V_{ABC_1}) = 178.804 \cdot \text{deg}$$

$$\arg(V_{ABC_2}) = 178.804 \cdot \text{deg}$$

Very close to ATP

$$I_{ABC} := A_{012} \cdot \begin{pmatrix} I_0 \\ I_1 \\ I_2 \end{pmatrix} \quad \vec{I}_{ABC} = \begin{pmatrix} 2.257 \\ 2.256 \\ 2.256 \end{pmatrix}$$

$$\vec{\arg(I_{ABC})} = \begin{pmatrix} -86.316 \\ -177.191 \\ 2.809 \end{pmatrix} \cdot \text{deg}$$

SLG or LL alone (without simultaneous):

- SLG

$$I_{0slg} := \frac{V_f}{(Z_{Bus1(M)}_{4,4} + Z_{Bus2(M)}_{4,4} + Z_{Bus0(M)}_{4,4})}$$

$$|I_{0slg}| = 0.752$$

$$\arg(I_{0slg}) = -86.316 \cdot \text{deg}$$

$$I_{A_slg} := 3 \cdot I_{0slg}$$

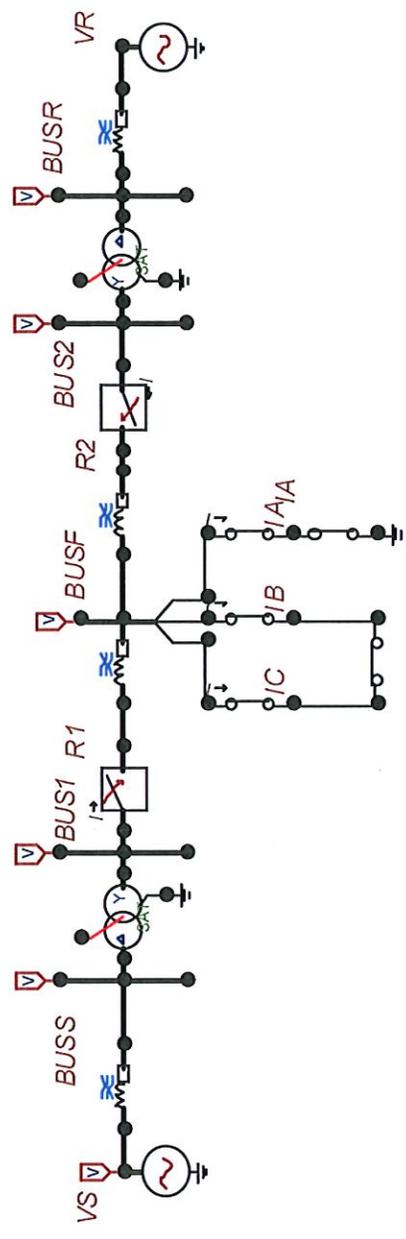
$$|I_{A_slg}| = 2.257 \cdot \text{pu}$$

$$\arg(I_{A_slg}) = -86.316 \cdot \text{deg}$$

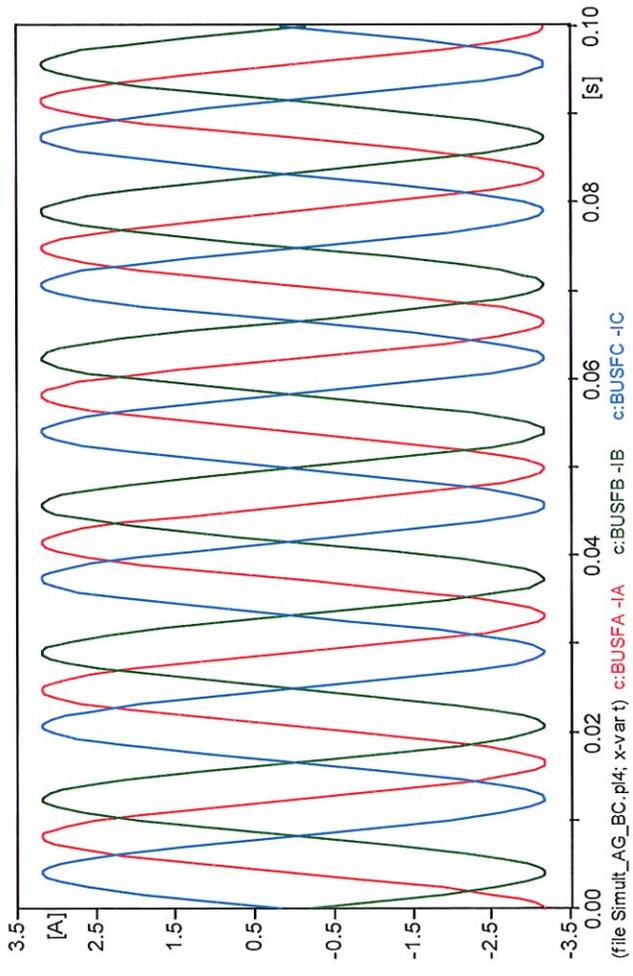
- Same as for simultaneous

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• **ATP System Model**



• **Fault Currents (versus time):**



• Note that: $I_C = -I_B$

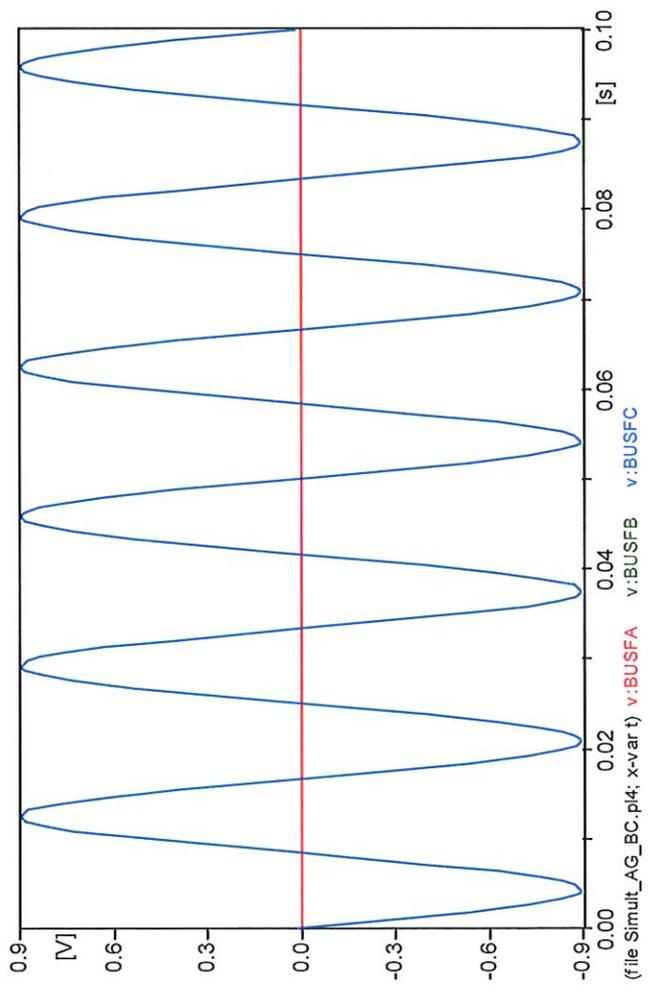
$|I_A| = 2.257A$ $\theta_A := -86.24deg$

$|I_B| = 2.257A$ $\theta_B := -177.1deg$

$|I_C| = 2.257A$ $\theta_C := 2.88deg$

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- Voltages at the fault point:



$$|V_{AG}| = 0V$$

$$|V_{BG}| = 0.6339V \quad \theta_{VB} := 178.9\text{deg}$$

$$|V_{CG}| = 0.6339V \quad \theta_{VC} := 178.9\text{deg}$$

