

Induction Machine Negative Sequence Example

$$\text{pu} := 1 \quad \text{MVA} := \text{MW}$$

Suppose that phase "a" of the supply an induction motor is opened. Find sequence voltages and currents if $V_{bc} = 1.0\text{pu}$ on a line to line basis.

Machine parameters:

$$V_b := 4\text{kV} \quad \text{Efficiency} := 0.93$$

$$P_{\text{out}} := 1000\text{hp} \quad \text{or in W} \quad P_{\text{out}} = 745.7\text{ kW}$$

$$P_{\text{in}} := \frac{P_{\text{out}}}{\text{Efficiency}} \quad P_{\text{in}} = 801.828\text{ kW}$$

$$\text{power_factor} := 0.90$$

$$S_{\text{in}} := \frac{P_{\text{in}}}{\text{power_factor}}$$

$$S_{\text{base1}} := S_{\text{in}} \quad S_{\text{base1}} = 0.891\text{ MVA}$$

$$\text{slip_rated} := 0.02$$

$$R_s := 0.02\text{pu} \quad X_s := 0.08\text{pu} \quad X_m := 3.0\text{pu}$$

$$R_r := 0.02\text{pu} \quad X_r := 0.08\text{pu} \quad \text{referred to stator}$$

$$I_a = 0 \quad V_{bc} = V_b - V_c$$

$$I_b = -I_c$$

Moving to sequence domain:

$$I_1 = -I_2 = j \cdot \frac{I_b}{\sqrt{3}}$$

$$V_{bc} = -j \cdot \sqrt{3} \cdot (V_1 - V_2)$$

$$\text{or} \quad V_1 - V_2 = j \cdot \frac{V_{bc}}{\sqrt{3}}$$

Therefore we connect the positive and negative sequence circuits in series and impose the voltage $V_1 - V_2$ across them (derived from the value of V_{bc})

Original voltage:

$$V_{ap} := 1 \text{ pu } e^{j \cdot 0 \text{ deg}} \quad V_{bp} := 1 \text{ pu } e^{-j \cdot 120 \text{ deg}} \quad V_{cp} := 1 \text{ pu } e^{j \cdot 120 \text{ deg}}$$

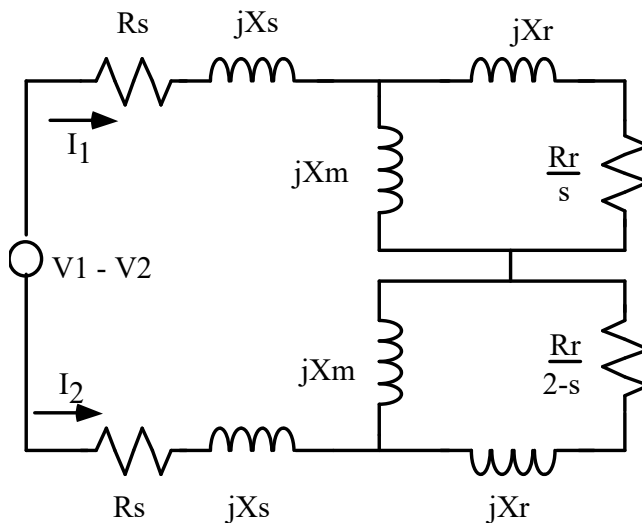
$$V_{bc} := V_{bp} - V_{cp} \quad |V_{bc}| = 1.732 \cdot \text{pu} \quad \arg(V_{bc}) = -90 \cdot \text{deg}$$

- *This is 1.0 per unit in the line to line voltage.....*

Then $V_1 - V_2$ is:

$$V_{1_2} := j \cdot \frac{V_{bc}}{\sqrt{3}} \quad V_{1_2} = 1 \cdot \text{pu} \quad \text{the problem was set up to use nice numbers}$$

Now we can solve the circuit below, where the positive and negative sequence circuits are connected in



- First come up with the equivalent circuit for the parallel combination in the two rotor circuits...

$$Z_{\text{pos_rot}} := \left(\frac{1}{j \cdot X_m} + \frac{1}{j \cdot X_r + \frac{R_r}{\text{slip_rated}}} \right)^{-1} \quad Z_{\text{pos_rot}} = (0.858 + 0.357i) \cdot \text{pu}$$

$$Z_{\text{neg_rot}} := \left(\frac{1}{j \cdot X_m} + \frac{1}{j \cdot X_r + \frac{R_r}{2 - \text{slip_rated}}} \right)^{-1} \quad Z_{\text{neg_rot}} = (9.583 \times 10^{-3} + 0.078i) \cdot \text{pu}$$

- Note how much smaller the real part of this expression is than for the positive sequence part.

$$I_{1_stator} = -I_{2_stator}$$

$$I_{1_stator} := \frac{V_{1_2}}{2(R_s + j \cdot X_s) + z_{pos_rot} + z_{neg_rot}}$$

$$I_{1_stator} = 0.771 - 0.505i$$

$$|I_{1_stator}| = 0.921 \cdot \text{pu}$$

$$\arg(I_{1_stator}) = -33.22 \cdot \text{deg}$$

$$I_{2_stator} := -I_{1_stator}$$

$$|I_{2_stator}| = 0.921 \cdot \text{pu}$$

$$\arg(I_{2_stator}) = 146.78 \cdot \text{deg}$$

$$V_1 := I_{1_stator} \cdot (R_s + j \cdot X_s + z_{pos_rot}) \quad V_1 = (0.897 - 0.107i) \cdot \text{pu}$$

$$|V_1| = 0.904 \cdot \text{pu}$$

$$\arg(V_1) = -6.788 \cdot \text{deg}$$

$$V_2 := I_{2_stator} \cdot (R_s + j \cdot X_s + z_{neg_rot}) \quad V_2 = (-0.103 - 0.107i) \cdot \text{pu}$$

$$|V_2| = 0.148 \cdot \text{pu}$$

$$\arg(V_2) = -133.828 \cdot \text{deg}$$

$$V_1 - V_2 = 1 \cdot \text{pu} \quad \text{as expected....}$$