

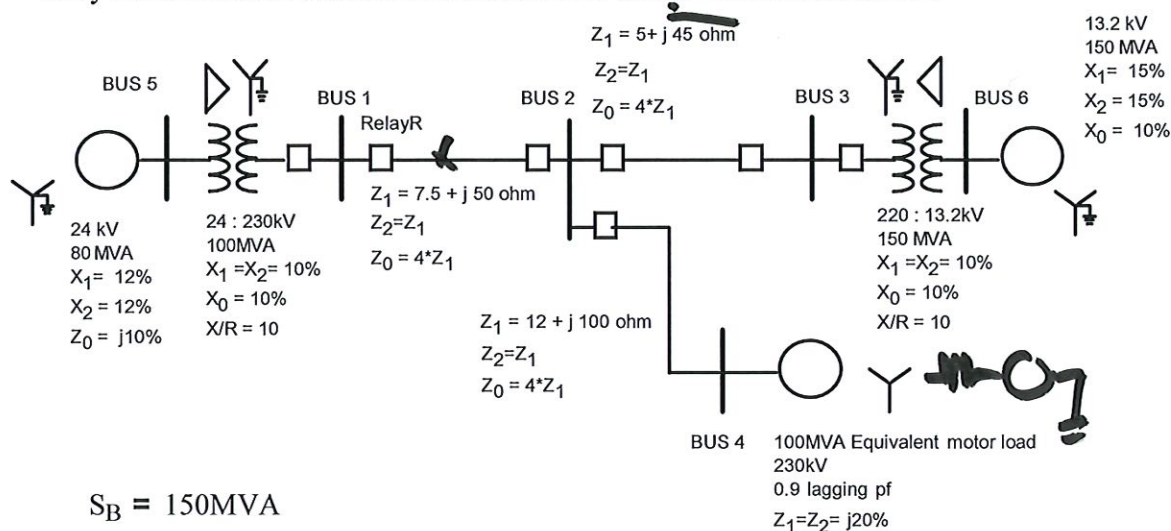
ECE 523
Symmetrical Components

Session 9

ECE 523: Homework #3

Due Session 13 (October 3)

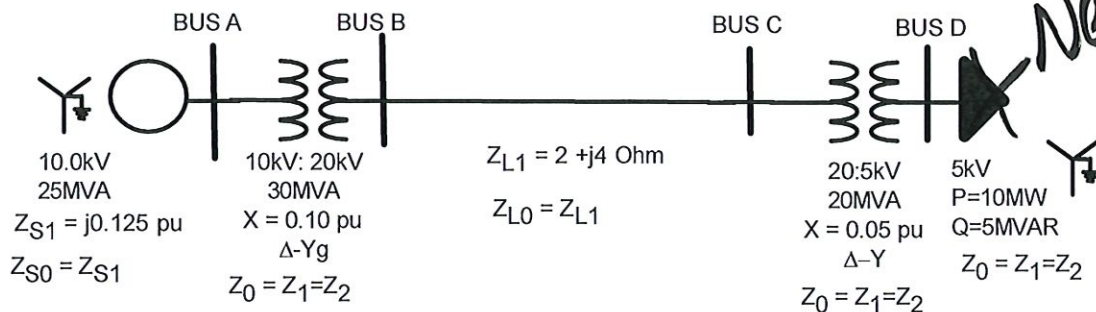
1. Create positive, negative and zero sequence Ybus and Zbus matrices for the system below to study faults on the line between BUS 1 and BUS 2. Use $M=0.45$ relative to Bus 1



Start voltage bases using rated voltage for the generator at BUS 5

2. Analyze the following faults. Use $S_{base}=25 \text{ MVA}$ and a voltage base of 5kV at BUS D. You can neglect load current in your fault current calculations. Treat all buses as being at 1.0pu magnitude prior to the fault. Calculate by hand and with a fault program

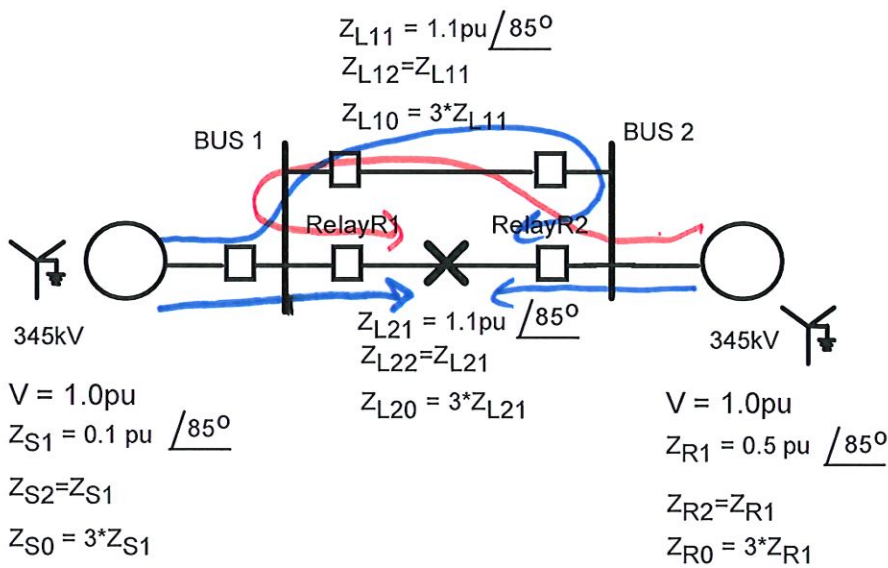
- Three phase fault at Bus C. Find V and I at the fault location and at BUS A
- SLG fault with $R_f=0$ at Bus C. Find V and I at the fault location and at BUS A
- LL fault with $R_f=0$ at Bus C. Find V and I at the fault location and at BUS A
- DLG fault with $R_f = R_g = 0$ at Bus C, Find V and I at the fault location and at BUS A
- Compare the fault current magnitudes and voltages between each of the different fault types
- Using your fault program, repeat parts a-e for faults at BUS B, and comment on how the results change with the fault location.



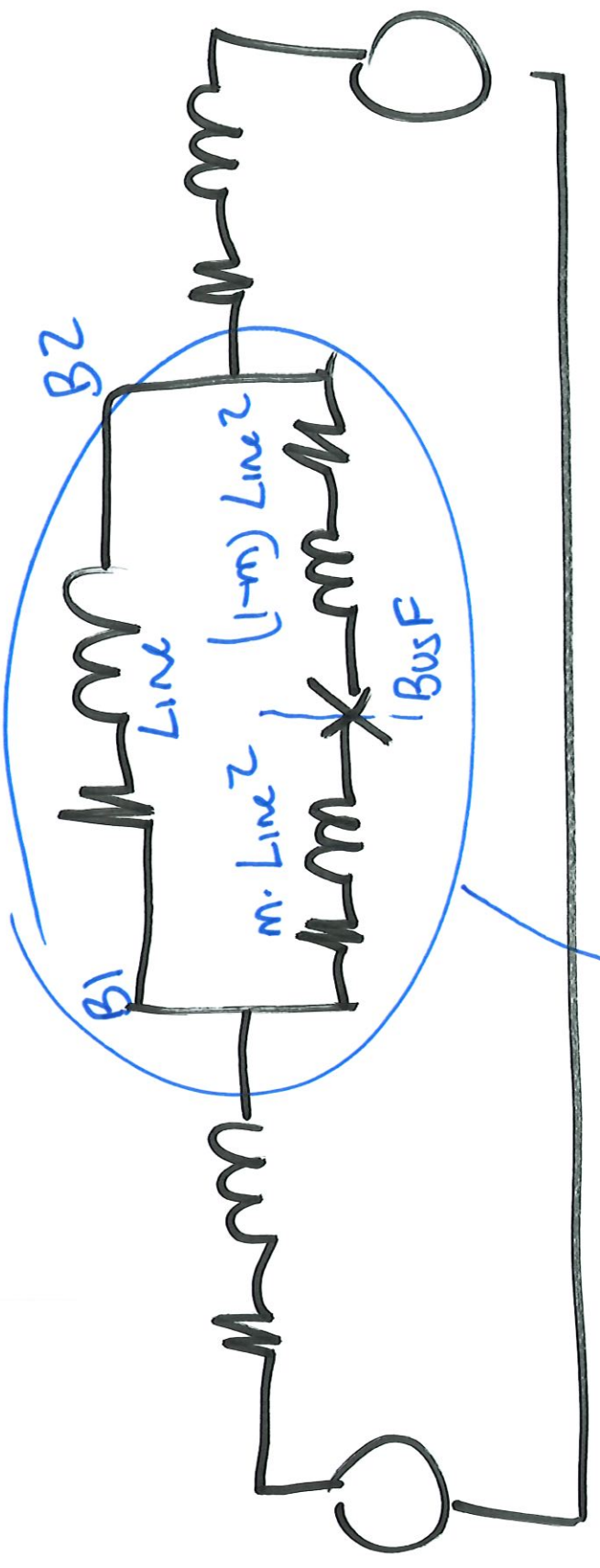
3. Do the following for the circuit below. **Also check your results with a commercial fault program and show comparison in tables.**

- Calculate and sketch the positive, negative and zero sequence equivalent circuits based on a fault 40% of the way down line 2 (the lower of the two lines). Get the Ybus matrices from your fault program.
- Calculate the voltages and currents at RelayR1 and RelayR2, for SLG, LL, and DLG faults with $R_f = 0$. I recommend using Zbus matrix methods.
- Repeat the part (b) for a SLG fault, LL, and DLG with $R_f = 0.75$ pu. For the DLG put the fault resistance in the neutral to ground path.

-compare to what you calculate



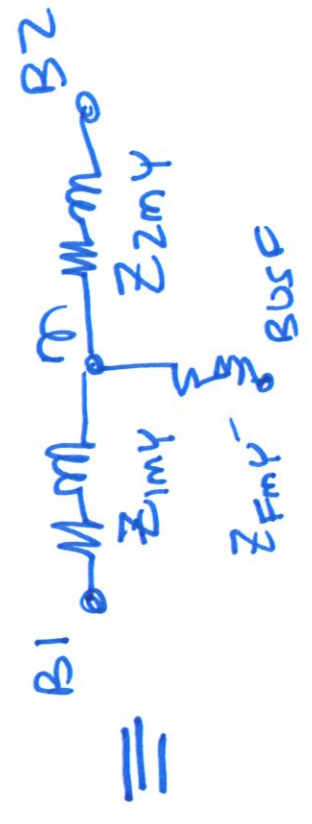
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Simplify

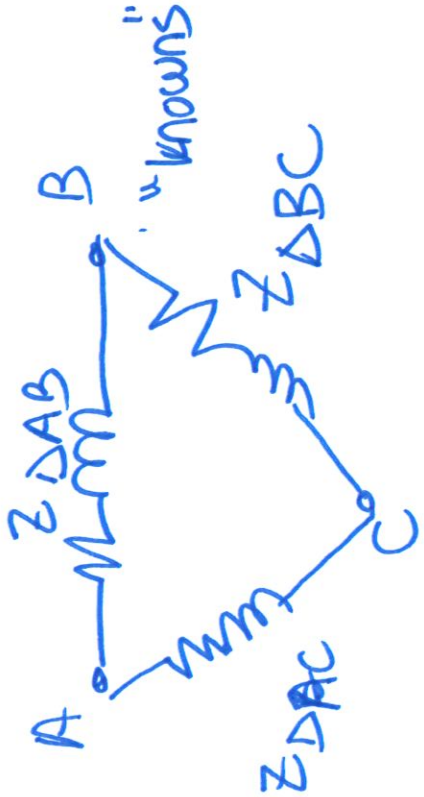


unbalanced Δ



unbalanced γ -pull

General Form of $\Delta - Y$ conversion

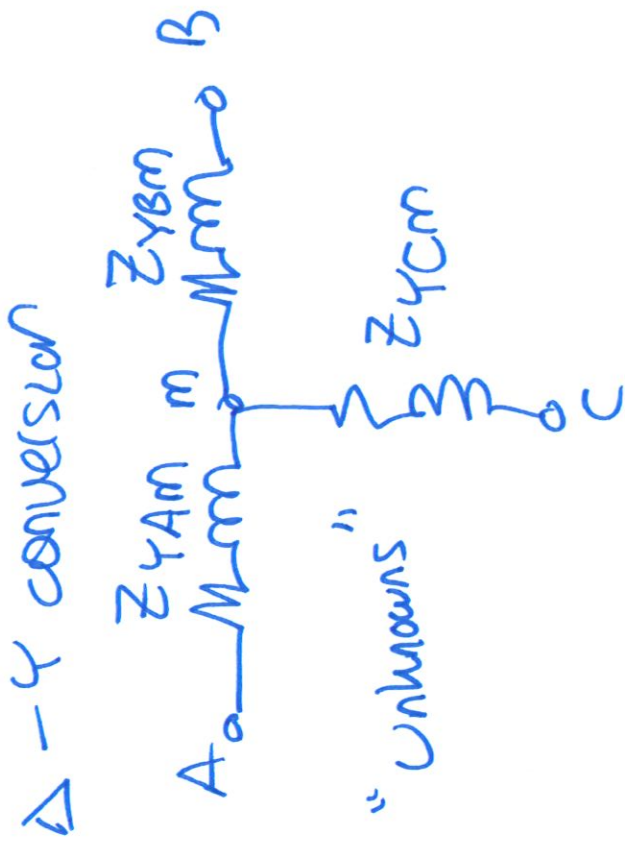


$$Z_{eq A B \Delta} = Z_{\Delta AB} \parallel (Z_{\Delta AC} + Z_{\Delta BC})$$

$$= \frac{(Z_{\Delta AB})(Z_{\Delta AC} + Z_{\Delta BC})}{Z_{\Delta AB} + Z_{\Delta AC} + Z_{\Delta BC}}$$

$$Z_{eq A \Delta} = Z_{eq A C Y}$$

$$Z_{eq B C \Delta} = Z_{eq B C Y}$$



$$Z_{eq A B Y} = Z_{Y A} + Z_{Y B}$$

$$Z_{eq A B \Delta} = Z_{eq A B Y}$$

3 equations, 3 unknowns

As a check, if balanced ..

$$Z_D, Z_Y$$

$$Z_{\varphi ABD} = \frac{Z_D(2Z_D)}{3Z_D}$$

$$Z_{\varphi ABY} = 2Z_Y$$

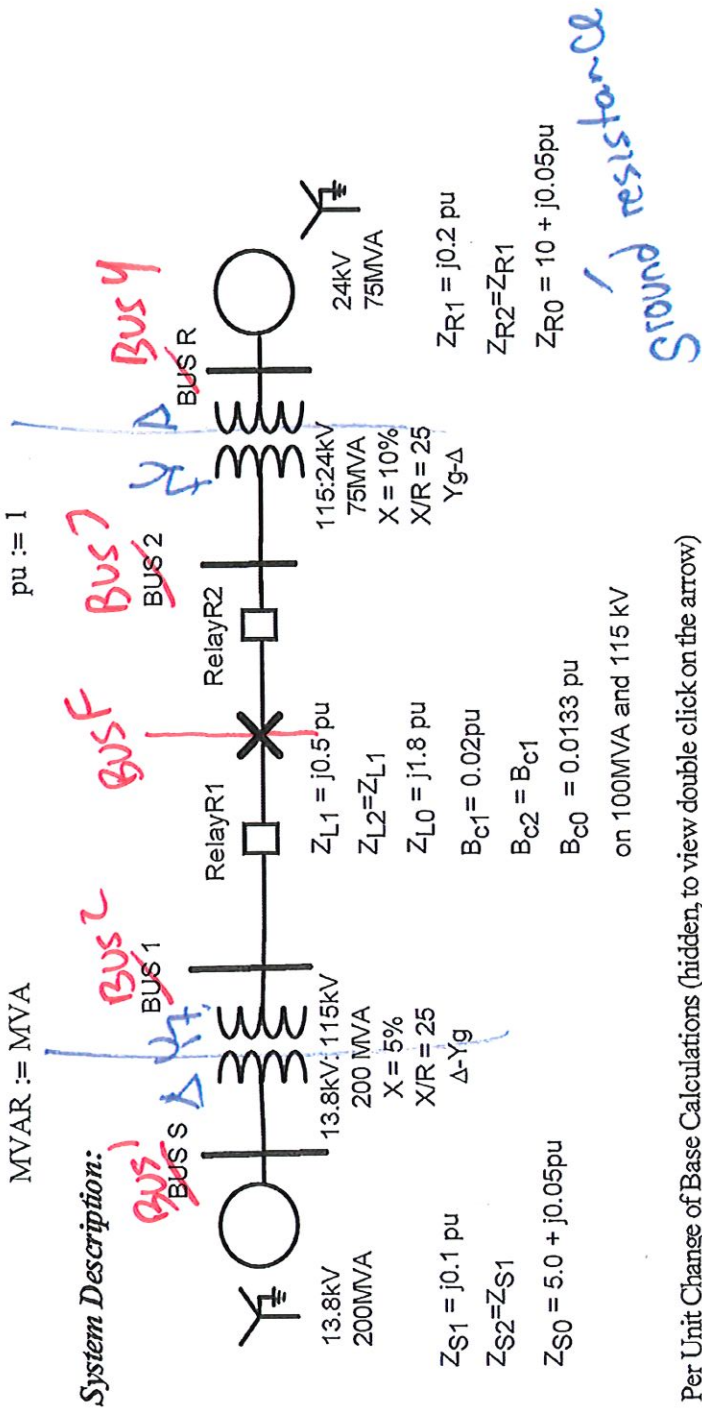
$$\cancel{\frac{2Z_D}{3}} = \cancel{2Z_Y}$$

$$\frac{Z_D}{3} = Z_Y$$

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Fault Analysis Techniques to Find Voltages and Currents at Other Buses With Transformer Phase Shifts

Define units: MVA := MW
MVAR := MVA

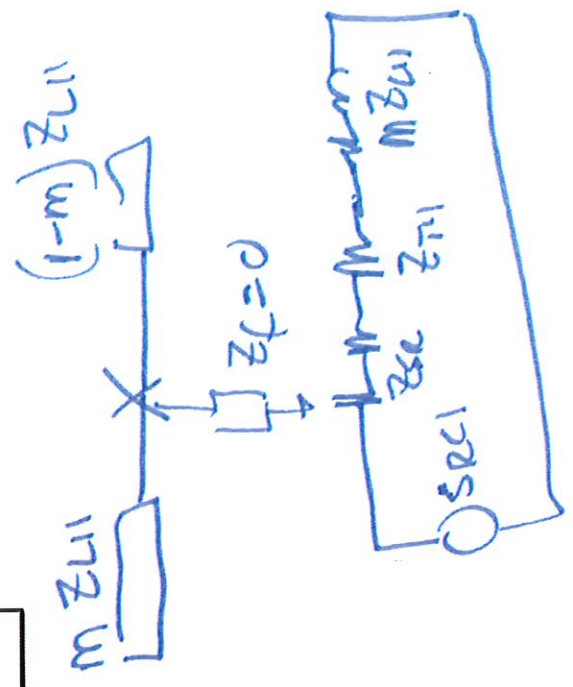
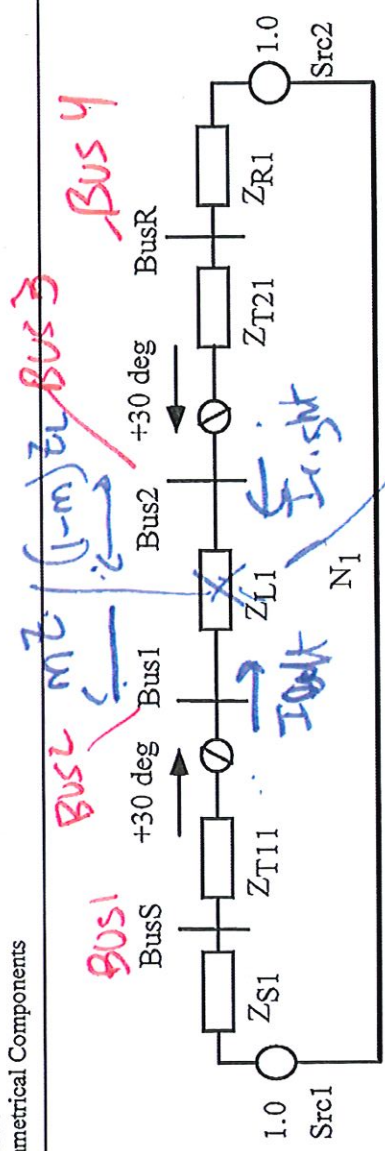


Per Unit Change of Base Calculations (hidden, to view double click on the arrow)

Set bases (Use the line voltage of 115kV as the reference):

$S_b := 100 \text{ MVA}$ $V_{b2} := 115 \text{ kV}$
 $V_{b1} := V_{b2} \cdot \frac{13.8 \text{ kV}}{115 \text{ kV}}$ $V_{b1} = 13.8 \text{ kV}$
 $V_{b3} := V_{b2} \cdot \frac{24 \text{ kV}}{115 \text{ kV}}$ $V_{b3} = 24 \text{ kV}$

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- Regular circuit analysis approach:
- Calculate reduced equivalent for several fault locations
- Use a generic location, M , and define a Mathcad function:

$$Z_{left}(M) := j \cdot X_{G11} + Z_{T11} + Z_{L11} \cdot M$$

$$Z_{right}(M) := Z_{L11} \cdot (1 - M) + Z_{T21} + j \cdot X_{G21}$$

$$Z_{1equiv}(M) := \left[\frac{1}{j \cdot X_{G11} + Z_{T11} + Z_{L11} \cdot M} + \frac{1}{Z_{L11} \cdot (1 - M) + Z_{T21} + j \cdot X_{G21}} \right]^{-1}$$

- More compactly: $Z_{1thv}(M) := \left(\frac{1}{Z_{left}(M)} + \frac{1}{Z_{right}(M)} \right)^{-1}$

$V_f := 1.0pu \rightarrow$ Both sources at 1.0 - referred to side of transformer with side of transformer

$$I_{3ph}(M) := \frac{V_f}{Z_{1equiv}(M)}$$

$$I_{3ph}(0.5) = -4.6154i$$

Total fault current on phase A

If $R_f \neq 0$

$$I_{3ph}(M, R_f) = \frac{V_f}{Z_{equiv}(M) + R_f}$$

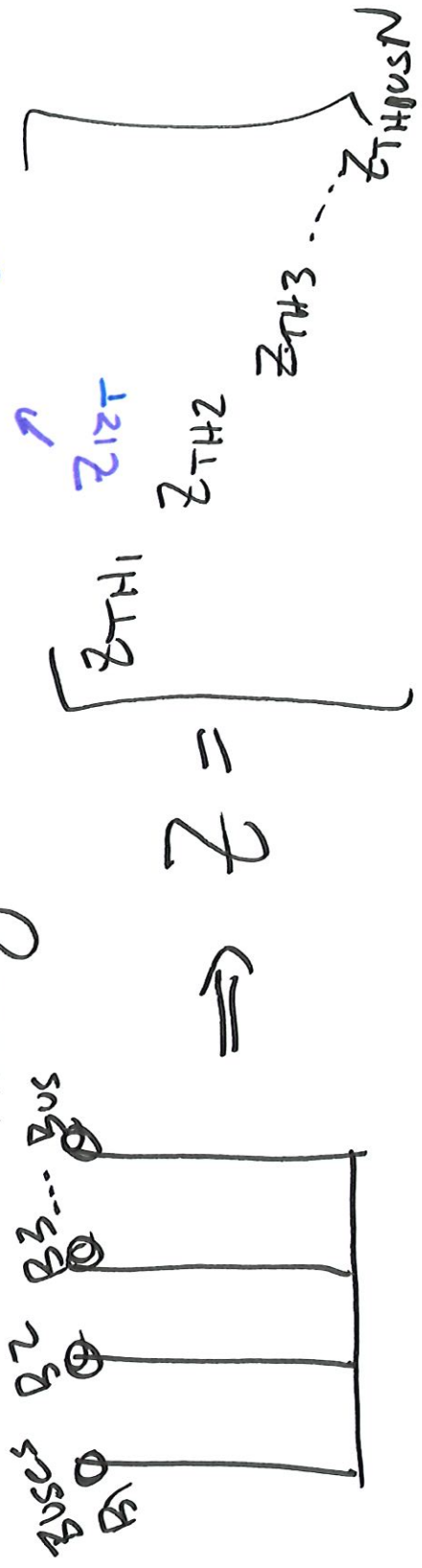
$M \approx 0.5$ Fault resistance

Z BUS Approach

- Bus impedance matrix
- can build directly from a circuit
- using circuit operators

- messy.

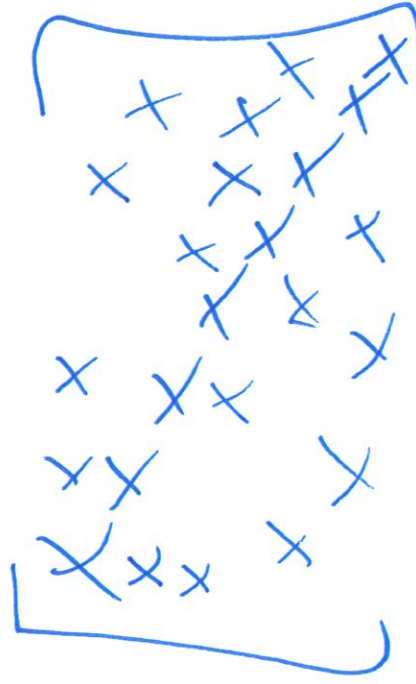
280 150 per unit for impedance



$$\Delta V_{BUS1} = Z_{12} \cdot I_{A2}$$

Get the ZBUS matrix by
inverting YBUS matrix

- YBUS is a sparse matrix

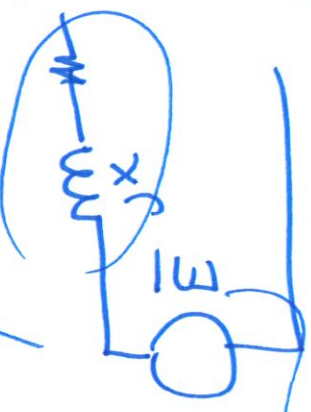


- symmetric locations
non zero

→ Partial sparse inverse
to get the elements needed.

Y BUS: for fault analysis. [pos, neg, zero sequence matrices]

- 1. Include internal impedances of generators (rotating machines) - YBUS and ~~large~~ motors



Inverter based - later
resources - in course

Calculate based on pre-fault load current

- 2. most programs neglect line capacitances (shunt)
- 3. model mutual coupling of parallel lines (zero sequence) - later in the course

4. Δ - $Y\frac{1}{2}$ (or other) transformers
connections - in sequence domain -

with
phase
shifts

↳ 3 winding transformers

Tap changes
Phase shifter

Diagonal elements of Y_{BUS}

$Y_{ii} \quad i \in [1, n]$

→ sum of admittances connected to that bus

→ Again: includes internal impedances of sources

Off diagonal elements

$$Y_{ij} \quad i \neq j$$

→ same rules as power flow Y_{BUS}

$$\vec{I}_{12} \rightarrow \frac{V_1 - V_2}{Z_{12}} \leftarrow \vec{I}_{21}$$

From Bus i to Bus j

$$\vec{I}_{12} = (\bar{V}_1 - \bar{V}_2) \bar{Y}_{12}$$

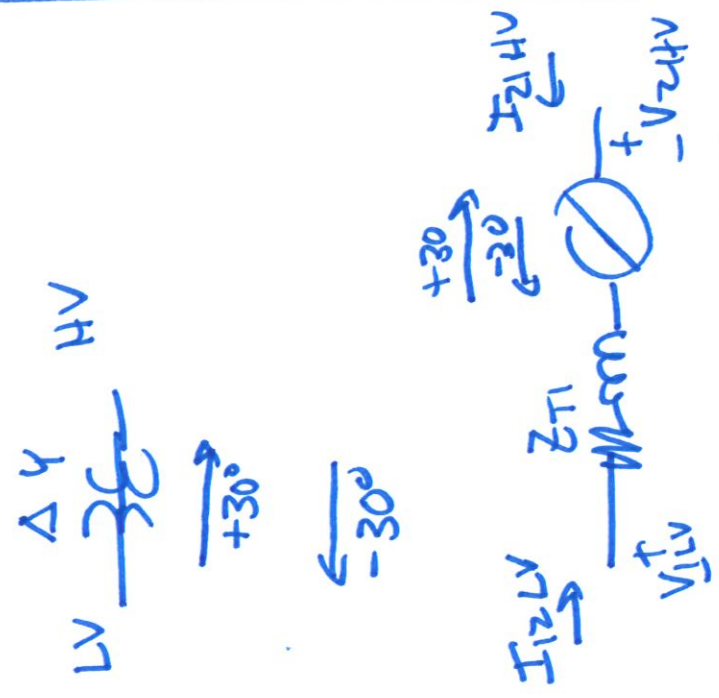
$$\vec{I}_{21} = (\bar{V}_2 - \bar{V}_1) \bar{Y}_{21}$$

$\bar{Y}_{12} = \bar{Y}_{21}$ for most equipment

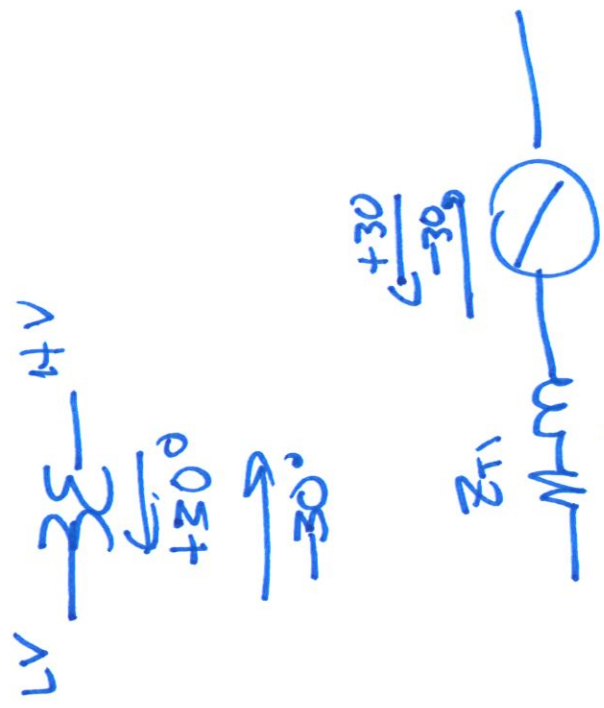
$$\begin{bmatrix} \vec{I}_{12} \\ \vec{I}_{21} \end{bmatrix} = \begin{bmatrix} \bar{Y}_{12} & -\bar{Y}_{12} \\ -\bar{Y}_{21} & \bar{Y}_{21} \end{bmatrix} \begin{bmatrix} \bar{V}_1 \\ \bar{V}_2 \end{bmatrix}$$

ΔY transformer

Pos sequence



neg sequence



Pos sequence

$\frac{1}{\sqrt{3}}$

$$\bar{I}_{12LV} = (\bar{V}_{1LV} - \bar{V}_{2HV}) \cdot Y_{TT}$$

refer to
Low voltage side

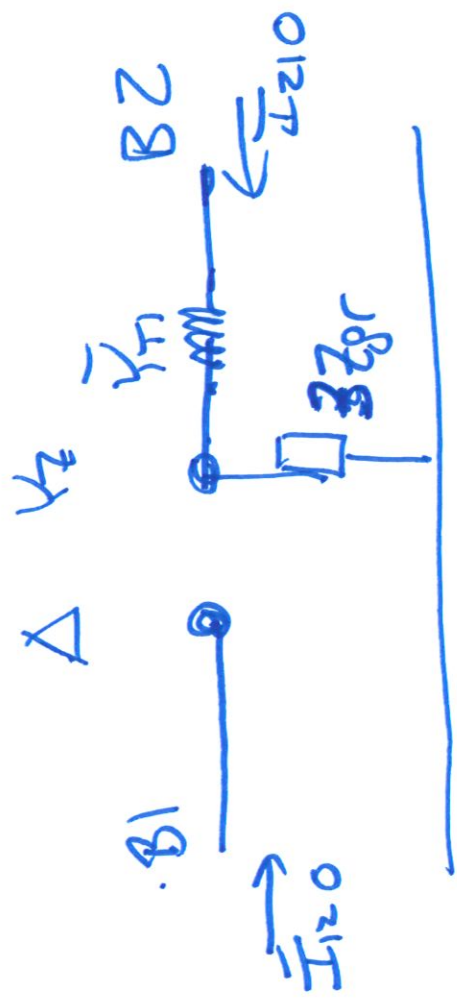
$$\bar{I}_{21HV} = (\bar{V}_{2HV} - \bar{V}_{1LV} \angle +30^\circ) Y_{TT}$$

matrix form

$$\begin{bmatrix} \bar{I}_{12LV} \\ \bar{I}_{21HV} \\ \bar{I}_{21HV} \end{bmatrix} = \begin{bmatrix} Y_{TT} & -Y_{TT} \angle -30^\circ \\ -Y_{TT} \angle +30^\circ & Y_{TT} \end{bmatrix} \begin{bmatrix} \bar{V}_{1LV} \\ \bar{V}_{2HV} \end{bmatrix}$$

ΔY_0 in zero sequence
 → NO phase shift

→ I_0 circulates in a Δ



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3 ZBUS Matrix Approach

Easiest Approach is to Create Ybus Matrix. Modified for Fault Calculations:

Transformer Phase Shift:

$$Y_1(M) := \begin{bmatrix} \frac{1}{jX_{G11}} + \frac{1}{Z_{T11}} & 0 & 0 & 0 & 0 \\ \frac{-1 \cdot e^{j \cdot 30 \text{deg}}}{Z_{T11}} & \frac{1}{Z_{T11}} + \frac{1}{M \cdot Z_{L11}} & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{Z_{T21}} + \frac{1}{(1-M) \cdot Z_{L11}} & \frac{-1 \cdot e^{j \cdot 30 \text{deg}}}{Z_{T21}} & \frac{-1}{(1-M) \cdot Z_{L11}} \\ 0 & 0 & \frac{-1 \cdot e^{-j \cdot 30 \text{deg}}}{Z_{T21}} & \frac{1}{Z_{T21}} + \frac{1}{jX_{G21}} & 0 \\ 0 & \frac{-1}{M \cdot Z_{L11}} & \frac{-1}{(1-M) \cdot Z_{L11}} & 0 & \frac{1}{M \cdot Z_{L11}} + \frac{1}{(1-M) \cdot Z_{L11}} \end{bmatrix}$$

BUS1 BUS2 BUS3 BUS4 BUS F

$$Z_1(M) := Y_1(M)^{-1}$$

$$Z_1(0.5) = \begin{bmatrix} 0.0474i & 0.0231 + 0.04i & 0.0103 + 0.0178i & 0.0137i & 0.0167 + 0.0289i \\ -0.0231 + 0.04i & 0.0692i & 0.0308i & -0.0103 + 0.0178i & 0.05i \\ -0.0103 + 0.0178i & 0.0308i & 0.2359i & -0.0786 + 0.1362i & 0.1333i \\ 0.0137i & 0.0103 + 0.0178i & 0.0786 + 0.1362i & 0.1937i & 0.0444 + 0.077i \\ -0.0167 + 0.0289i & 0.05i & 0.1333i & -0.0444 + 0.077i & 0.2167i \end{bmatrix}$$